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## Area Efficient Self Timed Adders For Low Power Applications in VLSI

S.Bharathi, M.SunandhaPreethi

Assistant Professor, Dept. of ECE, Adhiparasakthi Engineering College, Melmaruvathur, TamilNadu, India

PG Student [VLSI design], Department. of ECE, Adhiparasakthi Engineering College, Melmaruvathur, TamilNadu, India

**ABSTRACT:** In today's world there is a great need for low power design and area efficient high performance in DIP (Digital Image Processing) system. In this paper the proposed method presents a parallel single-rail self-timed adder. It uses recursive method for performing multi bit binary addition. This design attains good performance without any special speedup circuitry. A practical implementation is provided along with a completion detection unit. The implementation is regular and does not have any practical limitations of high fan outs. The recursive method based adder consumes least power among other Self-timed adders. In our work this can be reduced with proposed adder. This technique presents a pre-processing and post processing adder to minimize the multiplier technique. A high fan-in gate is required though but this is unavoidable for asynchronous logic and is managed by connecting the transistors in parallel. Simulations have been performed using cadence tool and superiority of the proposed approach over existing asynchronous adders. In this proposed system we are using a parallel prefix adder it is used to reduce the power consumption, area efficiently. Simulation of this technique is carried out by the cadence tool CADENCE GPDK 180nm Technology

**KEYWORDS:** Asynchronous circuits, binary adder. CMOS design digital arithmetic, multiplier technique.

### I. INTRODUCTION

Low power has emerged as a principal theme in today's electronics industry. The need for low power has caused a major paradigm shift where power dissipation has become as important a consideration as performance and area. So this Binary addition is the single most important operation that a processor performs. Polonky et al. (1999) proposed a self-timed adder based on DI RSFQ primitives. Self-timed or asynchronous design solves these problems by removing a global clock. Most of the adders have been designed for synchronous circuits even though there is a strong interest in clockless/asynchronous processors/circuits. Asynchronous circuits do not assume any quantization of time. Therefore, they hold great potential for logic design as they are free from several problems of clocked (synchronous) circuits. Aniset et al. (2002) presented a theory based on PMOS devices need to be sized up to attain the gate's performance. In principle, logic flow in asynchronous circuits is controlled by a request-acknowledgment handshaking protocol to establish a pipeline in the absence of clocks. Explicit handshaking blocks for small elements, such as bit adders, are expensive. Cornelius et al. (2006) presented a new technique these dynamic circuits are often favoured in high performance designs because of the speed advantage offered over static CMOS logic circuit. Therefore, it is implicitly and efficiently managed using dual-rail carry propagation in adders. In this principle, logic flow in asynchronous circuits is mainly controlled by a request-acknowledgment handshaking protocol to establish a pipeline in the absence of clocks. Explicit handshaking blocks for small elements, such as bit adders, are expensive. Choudary et al. (2010) presented a technique based on which they proposed an addition operation since in ALU all other arithmetic operations can be derived in terms of addition operation only. Therefore, it is implicitly and efficiently managed using dual-rail carry propagation in adders. Self-timed refers to logic circuits that depend on and/or engineer timing assumptions for the correct operation. Self-timed adders have the potential to run faster averaged for dynamic data, as early completion sensing can avoid the need for the worst case bundled delay mechanism of synchronous circuits.

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## PIPELINED ADDERS USING SINGLE RAIL ENCODING

The asynchronous Req/Ack handshake can be used to enable the adder block as well as to establish the flow of carry signals. These dual-rail signals can represent more than two logic values (invalid, 0, 1) and therefore can be used to generate bit-level acknowledgment when a bit operation is completed.

## DELAY INSENSITIVE ADDERS USING DUAL RAIL ENCODING

Delay insensitive (DI) adders are asynchronous adders that assert bundling constraints or DI operations. There are many variants of DI adders, such as DI ripple carry adder (DIRCA) and DI carry look-ahead adder (DICLA). DI adders use dual-rail encoding and are assumed to increase complexity.

## GENERAL BLOCK DIAGRAM OF PASTA

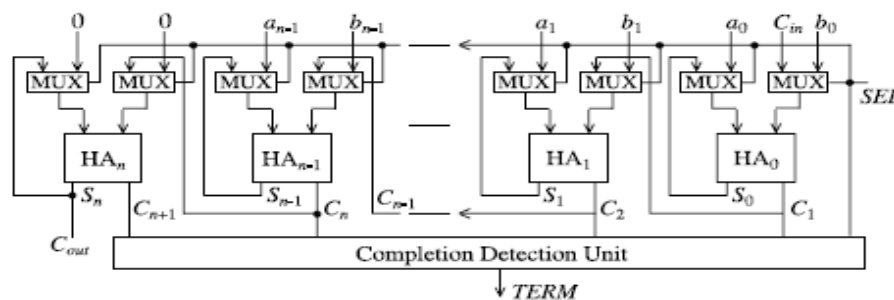


Fig. 1. General block diagram of PASTA.

The general architecture of the adder is shown in Fig. 1. The selection input for two-input multiplexers corresponds to the Req handshake signal and will be a single 0 to 1 transition denoted by SEL. It will initially select the actual operands during SEL = 0 and will switch to feedback/carry paths for subsequent iterations using SEL = 1. The feedback path from the HAs enables the multiple iterations to continue until the completion when all carry signals will assume zero values. C.

## II. RECURSIVE FORMULA FOR BINARY ADDITION

Let  $S_{ji}$  and  $C_{j+1}$  denote the sum and carry, respectively, for  $i$ th bit at the  $j$ th iteration. The initial condition ( $j = 0$ ) for addition is formulated as follows

$$S_{0i} = a_i \oplus b_i \tag{1.1}$$

$$C_{0i+1} = a_i b_i \tag{1.2}$$

The  $j$ th iteration for the recursive addition is formulated by

$$S_{ji} = S_{j-1,i} \oplus C_{j-1,i} \quad 0 \leq i < n \tag{1.3}$$

$$C_{ji+1} = S_{j-1,i} C_{j-1,i} \quad 0 \leq i \leq n \tag{1.4}$$

The recursion is terminated at  $k$ th iteration when the following condition is met:

$$C_{kn} + C_{k,n-1} + \dots + C_k = 0, \quad 0 \leq k \leq n$$

## III. PROPOSED ADDER

The addition of two binary numbers can be formulated as a prefix problem. A new technique for high speed in speculative completion. The corresponding parallel-prefix algorithms can be used for speeding up binary addition and for illustrating and understanding various addition principles. This section introduces a mathematical and visual formalism for prefix problems and algorithms.

Two categories of prefix algorithms can be distinguished; the serial prefix, and the tree Prefix Problems.

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In a prefix problem,  $n$  outputs ( $y_{n-1}, y_{n-2}, \dots, y_0$ ) are computed from  $n$  inputs ( $x_{n-1}, x_{n-2}, \dots, x_0$ ) using an arbitrary associative operator  $\bullet$  as follows

$$y_0 = x_0 \tag{1.5}$$

$$y_1 = x_1 \bullet x_0 \tag{1.6}$$

$$y_2 = x_2 \bullet x_1 \bullet x_0 \tag{1.7}$$

.

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$$y_{n-1} = x_{n-1} \bullet x_{n-2} \cdots \bullet x_1 \bullet x_0 \tag{1.7}$$

The problem can also be formulated recursively

$$y_0 = x_0 \tag{1.8}$$

$$i = 1, 2, \dots, n-1$$

$$y_i = x_i \bullet y_{i-1}; \tag{1.9}$$

Tree-prefix algorithms include parallelism for calculation speed-up, and therefore form the category of parallel-prefix algorithms. It represents a serial algorithm for solving the prefix problem. In the prefix tree, there are  $n$  columns, corresponding to the number of input bits. The gates performing the  $\bullet$  operation and which work in parallel are arranged in the same row, and similarly, the same gates connected in series are placed in consecutive rows. Thus, the number of rows  $m$  corresponds to the number of binary operations to be evaluated in series. The sum bits,  $s_i$  are finally obtained from a post processing step.

$$g_i = a_i \cdot b_i$$

$$p_i = a_i \oplus b_i;$$

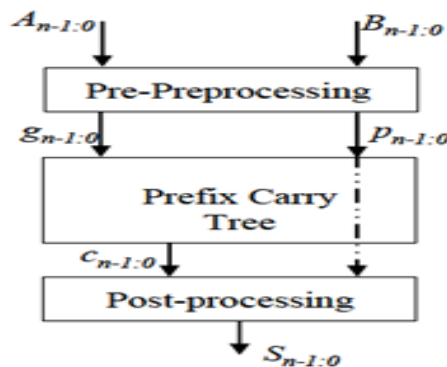


Fig 1.2 Block Diagram of Parallel Prefix Adder

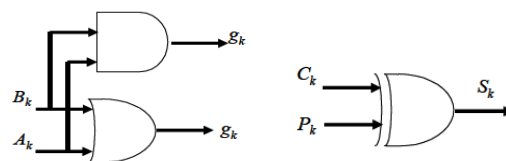


Fig 1.3 Logic and symbols for Pre processing summation Gates

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$$G_i = A_i \cdot B_i \tag{1.10}$$

$$K_i = \overline{A_i + B_i} = \overline{A_i} \cdot \overline{B_i} \tag{1.11}$$

$$P_i = \overline{A_i \oplus B_i} \tag{1.12}$$

In the above equation, ‘.’ operator is applied on two pairs of bits and, these bits represent generate and propagate signals used in addition. The output of the operator is a new pair of bits which is again combined using a dot operator ‘.’ or semi-dot operator ‘.’ with another pairs of bits. This procedural use of dot operator ‘.’ and semi-dot operator ‘.’ creates a prefix tree network which ultimately ends in the generation of all carry signals. In the final step, the sum bits of the adder are generated with the propagate signals of the operand bits and the preceding stage carry bit using a xor gate. Choudary(2008) proposed a new technique for basic arithmetic operation for higher automation. The semi-dot operator ‘.’ will be present as last computation node in each column of the prefix graph structures, where it is essential to compute only generate term, whose value is the carry generated from that bit to the succeeding iterations

## IV. MAC

The Multiply-Accumulate Unit (MAC) is the main computational kernel in DIP architectures. The MAC unit determines the power and the speed of the overall system; it always lies in the critical path. Developing high speed and low power MAC is crucial to use DSP in the future WSN. In this work, a fast and low power MAC Unit is proposed for 2D-DCT computation. Multiplication involves the generation of partial products, one for each digit in the multiplier, These partial products are then summed to produce the final product. The Multiply-Accumulate Unit (MAC) is the main computational kernel in DIP architectures. The MAC unit determines the power and the speed of the overall system; it always lies in the critical path. Developing high speed and low power MAC is crucial to use DSP in the future WSN. In this work, a fast and low power MAC Unit is proposed for 2D-DCT computation. Multiplication involves the generation of partial products, one for each digit in the multiplier, These partial products are then summed to produce the final product.

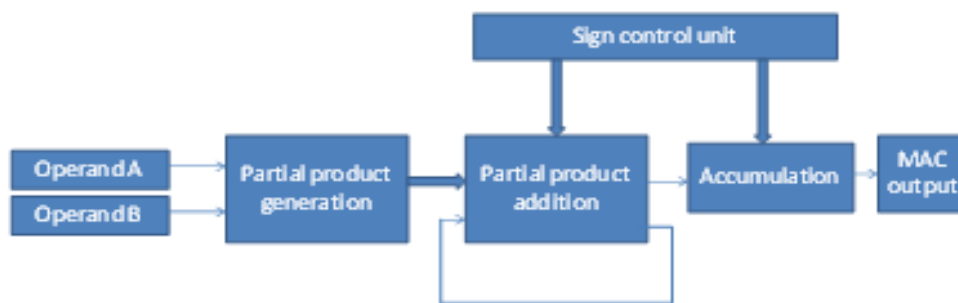


Fig 1.4 Block diagram of Proposed MAC

## V. MULTIPLICATION THROUGH ADDERS

Let the product register size be 16 bits. Let the multiplicand registers size be 8 bits. Store the multiplier in the least significant half of the product register. Clear the most significant half of the product register.

Repeat the following steps for 8 times:

- If the least significant bit of the product register is "1" then add the multiplicand to the most significant half of the product register.
- Shift the content of the product register one bit to the right (ignore the shifted-out bit.)
- Shift-in the carry bit into the most significant bit of the product register

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Multiplier is the main computational kernel in DIP architectures. The Multiplier unit determines the power and the speed of the overall system. In this work, proposed adder based on fast and low complexity Multiplier Unit is proposed. In all DSP and image processing application Multiplier will be the basic unit. The overall performance is fully depends on Adder unit efficiency. Multiplication involves the generation of partial products, one for each digit in the multiplier, These partial products are then summed to produce the final produced.

## VI. SIMULATIONS RESULTS

Simulation results Simulation output is to be obtained by using CADENCE in digital design environment. The adder was designed using multiplication technique. In this method usage the area, power consumption and time are obtained

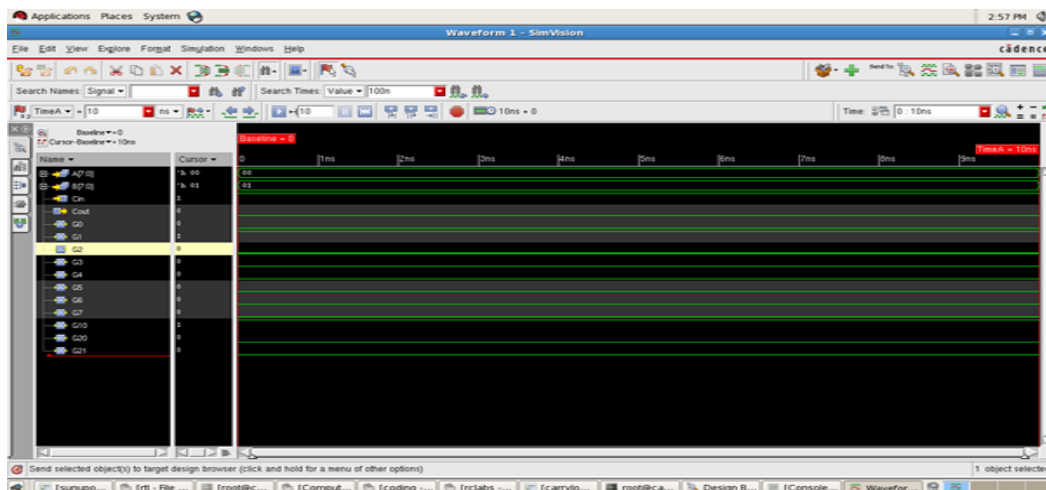


Fig 1.5 Simulation for Parallel Prefix Adder

Figure 4.1 shows the simulation results of parallel prefix adder. It represents 8 bit hexadecimal values hence clock is not assigned. The timing is varied for simulation the carry and propagate values are described for each input and output values are assigned using the force operation the run time is varied for each simulation.

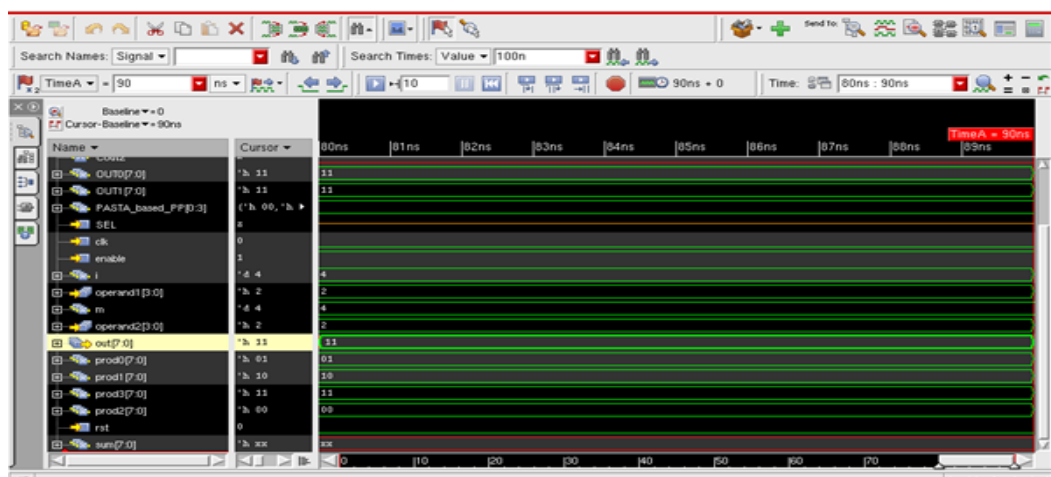


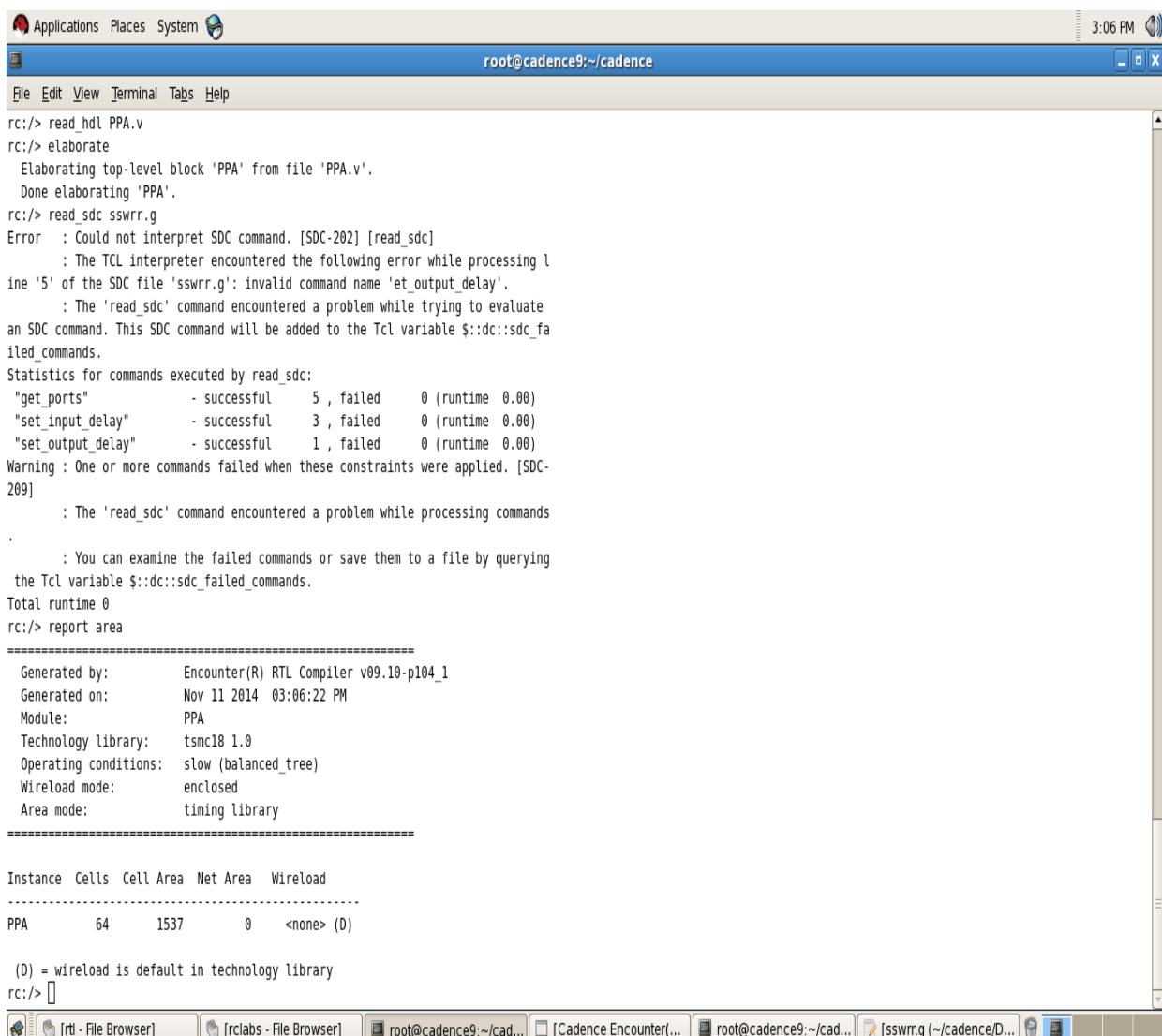
Fig 1.6 Simulations For Multiplier output

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Figure 4.10 shows the above result is the simulation waveform for multiplier technique using proposed adder. The clock and enable operations are performed the clock value is 0 and enable operation is 1 the 4 bit are assigned multiplier technique the values are displayed in hexadecimal values the pasta pins act as a calling function for each operation and run time for each bit is discussed the reset option is 0 the sum and carry operation performs 8 bit representation the sel act as a selection operation for input the product is multiplied using adder the each bit shifts to the previous for shift operation and hence multiplier is achieved



```

rc:/> read_hdl PPA.v
rc:/> elaborate
Elaborating top-level block 'PPA' from file 'PPA.v'.
Done elaborating 'PPA'.
rc:/> read_sdc sswrr.g
Error : Could not interpret SDC command. [SDC-202] [read_sdc]
       : The TCL interpreter encountered the following error while processing l
       : ine '5' of the SDC file 'sswrr.g': invalid command name 'et_output_delay'.
       : The 'read_sdc' command encountered a problem while trying to evaluate
       : an SDC command. This SDC command will be added to the Tcl variable $::dc::sdc_fa
       : iled_commands.
Statistics for commands executed by read_sdc:
"get_ports"      - successful  5 , failed  0 (runtime 0.00)
"set_input_delay" - successful  3 , failed  0 (runtime 0.00)
"set_output_delay" - successful  1 , failed  0 (runtime 0.00)
Warning : One or more commands failed when these constraints were applied. [SDC-
209]
       : The 'read_sdc' command encountered a problem while processing commands
       :
       : You can examine the failed commands or save them to a file by querying
       : the Tcl variable $::dc::sdc_failed_commands.
Total runtime 0
rc:/> report area
=====
Generated by:      Encounter(R) RTL Compiler v09.10-p104_1
Generated on:     Nov 11 2014 03:06:22 PM
Module:           PPA
Technology library: tsmc18 1.0
Operating conditions: slow (balanced_tree)
Wireload mode:    enclosed
Area mode:        timing library
=====

Instance  Cells  Cell Area  Net Area  Wireload
-----
PPA       64    1537      0         <none> (D)

(D) = wireload is default in technology library
rc:/>

```

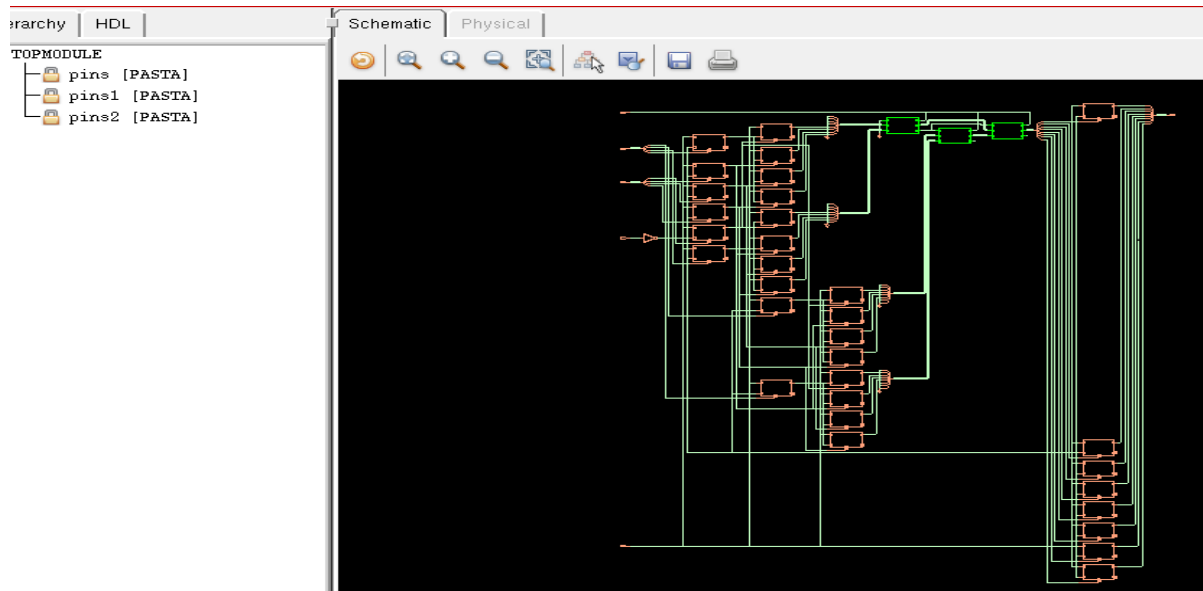
Fig 1.7 Area for proposed adder

Figure 1.7 shows the area window for proposed adder and hence area is 1537 for proposed method and hence compared with the existing system the cells are assigned with 64 cells the delay timing is less achieved for proposed system the timing analysis is achieved for high performance the 16 bit values are assigned with hexadecimal and calling function is separately assigned for each module the area is reduced when compared with the existing system using pasta module

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**Fig1.8** RTL View of Multiplier Output

Figure 1.8 shows the RTL view of multiplier output assigned with pasta blocks in the circuit. The blocks are assigned separately for each module, and pasta pins act as a calling function for each value in the multiplier technique. The separate module acts as a calling function for each block. Finally, the product is assigned with each bit in the multiplier technique using multiplication through an addition process. The mux acts as a calling function in the circuit. 16 bits are assigned for the multiplier technique.

## VII. CONCLUSION

A parallel prefix adder design is proposed for overall power consumption. The proposed adder provides overall area and power than the previous methods. The parallel asynchronous self-timed adder circuit is efficiently described using a handshaking protocol and also compared with other adders proposed adders. The MAC unit is implemented and the process is achieved efficiently. Simulation results demonstrate the effectiveness of the proposed framework in parallel prefix adder using multiplication through an addition process. The proposed method is implemented using the digital CADENCE environment.

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