



# **A High Step up Boost Converter Using Coupled Inductor with PI Control**

Saurabh<sup>1</sup>, Dr.P.K.Saha<sup>2</sup>, Dr.G.K.Panda<sup>3</sup>

PG Student [Power Electronics and Drives], Dept. of EE, Jalpaiguri Government Engineering College, Jalpaiguri,  
West Bengal, India<sup>1</sup>

Professor, Dept. of EE, Jalpaiguri Government Engineering College, Jalpaiguri, West Bengal, India<sup>2</sup>

Professor and HOD, Dept. of EE, Jalpaiguri Government Engineering College, Jalpaiguri, West Bengal, India<sup>3</sup>

**ABSTRACT:** The paper proposes a high step up boost converter. The proposed converter has used a coupled inductor with switched capacitors. The capacitors were made to get charged in parallel and were made to get discharged in series by the configuration to achieve high step up voltage gain. And the voltage across the load is maintained constant by using a closed loop control.

The operation and steady state analysis of the configuration has been shown in detail. Finally, a circuit with 24-V input, 400-V output, and power of 200W has been implemented in MATLAB software to verify the proper working and performance of the proposed configuration.

**KEYWORDS:** High step-up Boost Converter, Coupled Inductor, Switched Capacitor, PI Controller.

## **I.INTRODUCTION**

Boost converter is one of the most important and widely used devices of modern power applications. These converters are electronic devices used to change DC electrical power efficiently from one voltage level to another. They provide smooth acceleration control, high efficiency, and fast dynamic response. There are FOUR main types of converter usually called the buck, boost, buck-boost and Boost converters. The buck converter is used for voltage step-down/reduction, while the boost converter is used for voltage step-up. The buck-boost and Cuk converters can be used for either step-down or step-up.

Basically, the DC-DC converter consists of the power semiconductor devices which are operated as electronic switches and classified as switched-mode DC-DC converters. Operation of the switching devices causes the inherently nonlinear characteristic of the DC-DC converters. Due to this unwanted nonlinear characteristics, the converters requires a controller with a high degree of dynamic response. Pulse Width Modulation (PWM) is the most frequently consider method among the various switching control method. In DC-DC voltage regulators, it is important to supply a constant output voltage, regardless of disturbances on the input voltage.

Nowadays, the control systems for many power electronic appliances have been increasing widely. Crucial with these demands, many researchers or designers have been struggling to find the most economic and reliable controller to meet these demands. The idea to have a control system in dc-dc converter is to ensure desired voltage output can be produced efficiently as compared to open loop system. Controller for the PWM switching control is done by Proportional-Integral (PI) controller.

Many different methods have been proposed to improve the efficiency of the converter and to achieve high voltage gain, which can be done by using a switched capacitor and a coupled inductor is used for high gain by adjusting its turns ratio. Voltage spikes may occur due to the coupled inductor. For which we have used an active clamp circuit with coupled inductor which avoids voltage spikes.

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Figure 1 shows the block diagram of the proposed converter with closed loop control such that the voltage drift problem is minimized and the desired output is maintained. The output voltage was then taken as feedback and compared with desired value of output voltage and the difference is then fed to PI control which then produces the PWM signal to the switch of the converter.

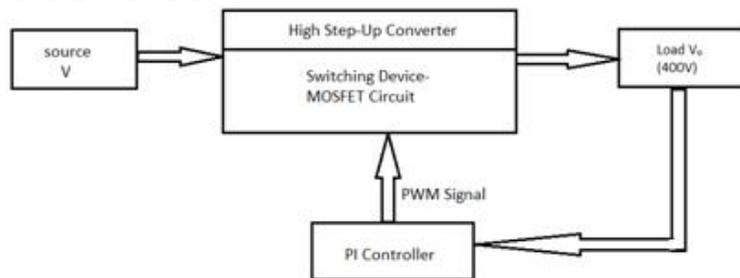


Figure 1 Proposed block diagram

## II.SYSTEM MODEL AND ASSUMPTIONS

Figure 2 shows the configuration of the proposed circuit. The circuit has a boost converter with coupled inductor, switched capacitor and a clamp circuit. The equivalent circuit of the coupled inductor consists of a magnetizing inductor  $L_m$ , leakage  $L_k$ , and an ideal transformer. The leakage inductor energy of the coupled inductor is recycled to capacitor  $C_1$ , and thus the voltage across the switch  $S$  can be clamped. The voltage across the capacitors  $C_2$ , and  $C_3$  can be adjusted by the turns ratio of the coupled inductor. For these reasons the voltage of switch is reduced significantly and low conducting resistance  $R_{ds(on)}$  of the switch can be used. Thus high step-up voltage gain can be achieved.

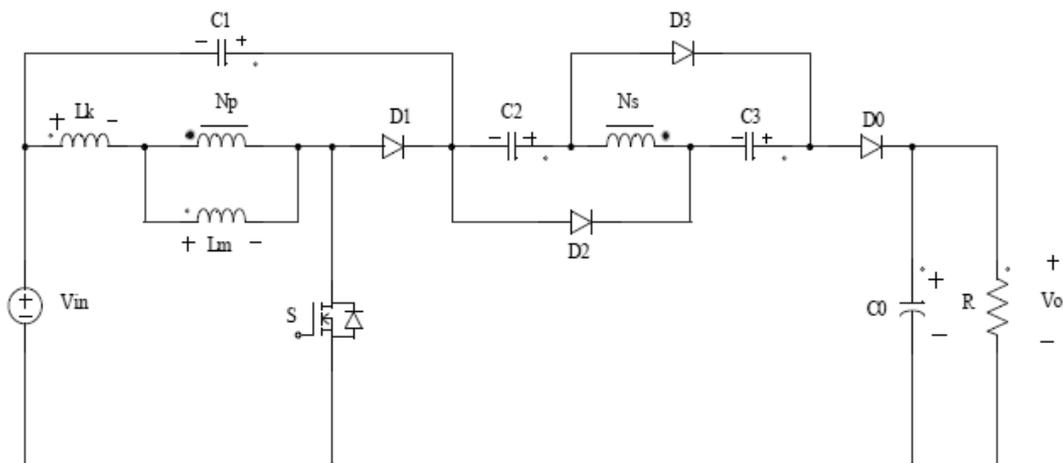


Figure 2 Circuit configuration of the proposed converter

To simplify the circuit analysis, these conditions have been assumed.

- Capacitors  $C_1$ ,  $C_2$ ,  $C_3$  and  $C_0$  are very large which makes voltages  $V_{C1}$ ,  $V_{C2}$ ,  $V_{C3}$  and  $V_0$  to be constant in one switching period.
- The power devices used are ideal, but the parasitic capacitance of the power switch was considered.
- The coupling coefficient of the coupled inductor  $k$  is equal to  $L_m/(L_s+L_k)$  and the turns ratio of the coupled inductor  $n$  is equal to  $N_s/N_p$ .

## III. MODES OF OPERATION AND ANALYSIS

There are five operating modes in one switching period.

- 1) Mode I ( $t_0, t_1$ ): Mode will start when the switch S is turned ON. Diodes  $D_1$  and  $D_0$  are off, and  $D_2$  and  $D_3$  are on. The current through  $L_k$  starts increasing linearly. The inductor  $L_m$  starts storing energy from the source voltage. Voltages  $V_{C_2}$  and  $V_{C_3}$  being connected in series to charge the output capacitor  $C_0$  which will then provide energy to the load. When current through  $D_0$  becomes zero, operating mode ends.
- 2) Mode II ( $t_1, t_2$ ): Here S will be kept ON. Diodes  $D_1, D_2$  and  $D_3$  are off and  $D_0$  is on. The  $L_m$  starts getting charged due to the source voltage. Capacitors  $C_2$  and  $C_3$  are also get charged due to the source via the coupled inductor. Capacitor  $C_0$  discharges to the load to maintain the desired output voltage. Switch S turns off to end the mode.
- 3) Mode III ( $t_2, t_3$ ): S is turned OFF in this mode. Diodes  $D_1, D_2$  and  $D_3$  are off, and  $D_0$  is on. Inductors  $L_k$  and  $L_m$  are discharged to the parasitic capacitor of the switch  $C_{ds}$ . Capacitor  $C_0$  continues to discharge and to provide energy to the load. Now the voltage across  $C_1$  is equal to  $V_{in} + V_{ds}$ , diode  $D_1$  now turned on and the mode ends.
- 4) Mode IV ( $t_3, t_4$ ): S is kept OFF. Diodes  $D_1$  and  $D_0$  are turned on and  $D_2$  and  $D_3$  are off. Inductors  $L_k$  and  $L_m$  are discharged to charge capacitor  $C_1$ .  $L_k$  gets discharged quickly. No current flows through the secondary side and  $L_2$  charges capacitor  $C_0$  and maintains the voltage across the load, which makes  $D_0$  to switch off and mode ends.
- 5) Mode V ( $t_4, t_5$ ): S is kept OFF. Diodes  $D_1, D_2$  and  $D_3$  are turned on and  $D_0$  is turned off. Inductors  $L_k$  and  $L_m$  are discharged to charge capacitor  $C_1$ . Making the voltage across the switch equals  $V_{in} + V_{C_1}$ . And  $L_2$  is charging both the capacitors  $C_2$  and  $C_3$ . The mode ends when the switch is turned ON and makes the next switching period.

## IV. SIMULATION RESULTS AND DISCUSSIONS

Figure 3 shows the MATLAB Simulation diagram of a high step-up boost converter using coupled inductor with PI control. The duty ratio of the switch is adjusted by PI Controller to obtain the require output.

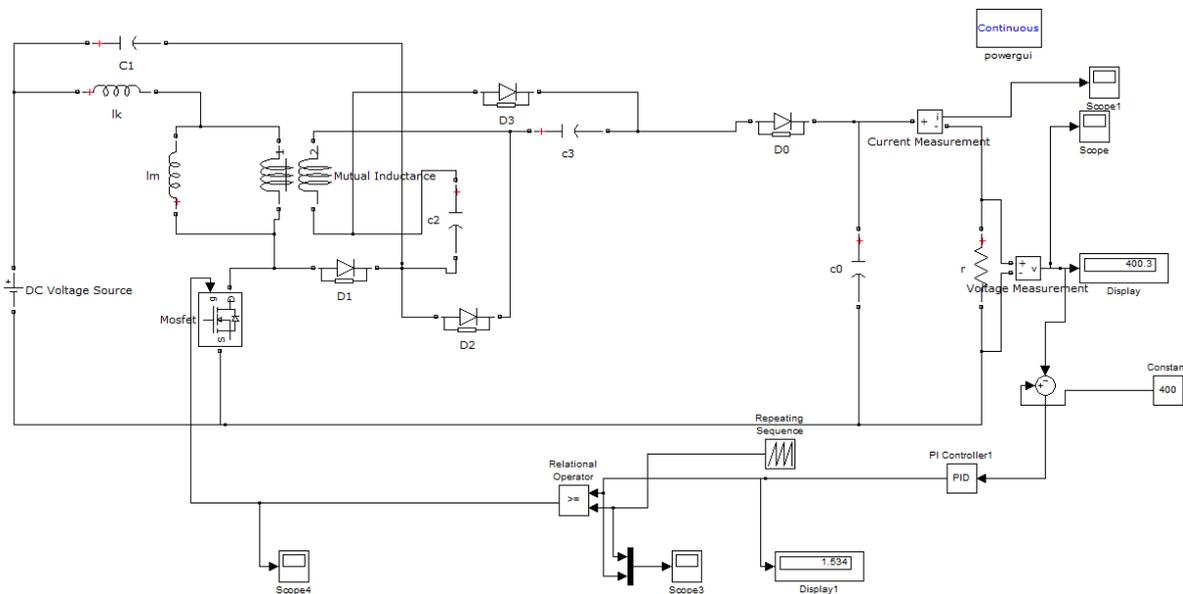


Figure 3 MATLAB Simulation Diagram of proposed converter with PI controller.

Figure 4 shows the output voltage  $V_0=400.3V$  with 18.75% maximum peak overshoot and the output voltage is well controlled by PI controller feedback.

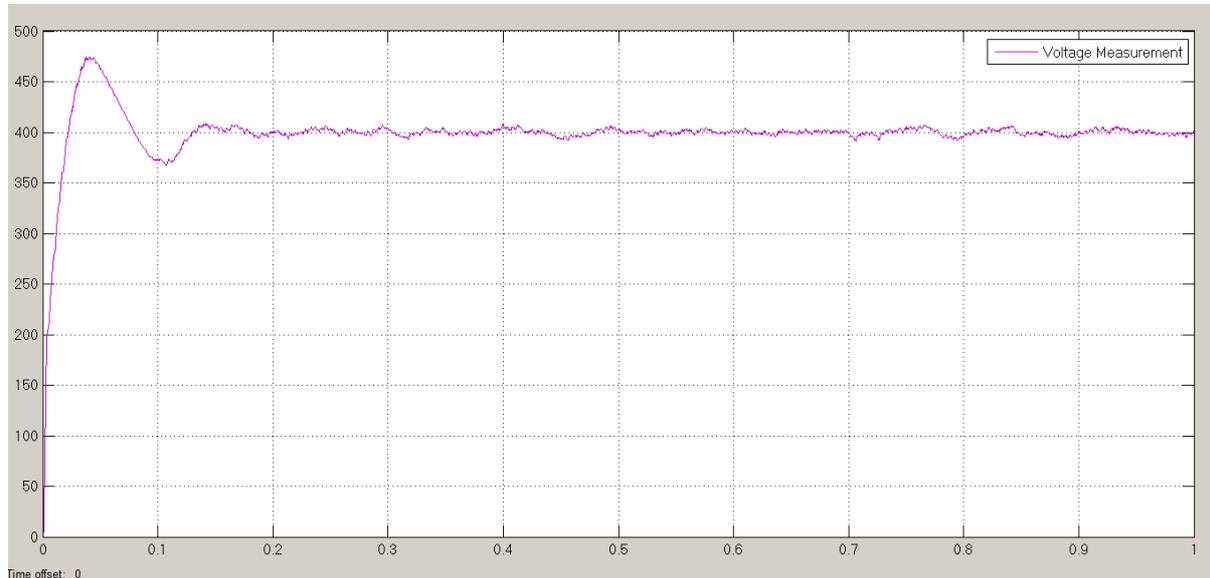


Figure 4 Output voltage ( $V_0=400.3V$ ).

Figure 5 shows the output current of 0.5A which shows the proposed controller was well able to control the output current as desired.

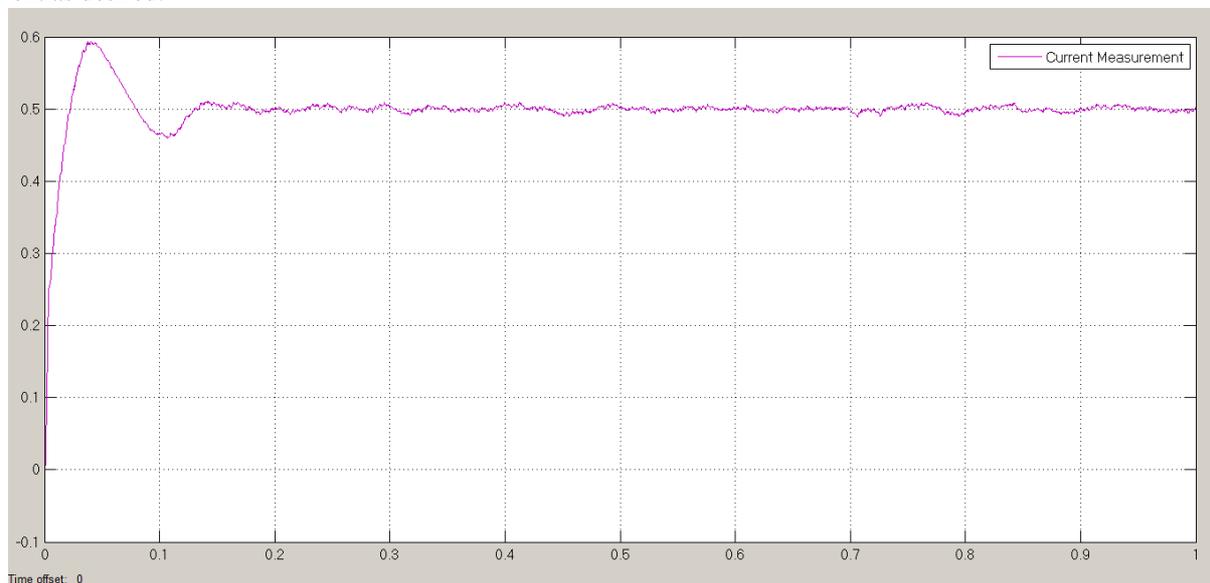


Figure 5 Output Current ( $I_0=0.5A$ ).

Figure 6 shows the pulse generated and given to the switch for its proper working and the maintenance of the desired output.

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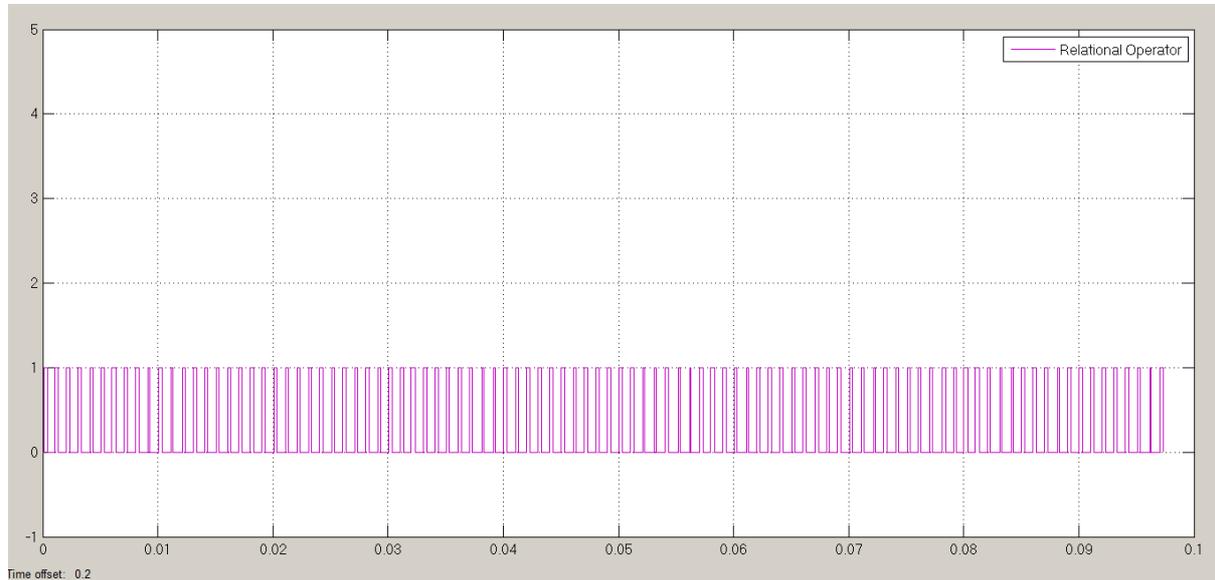


Figure 6 Pulse generated by PI controller for the switch.

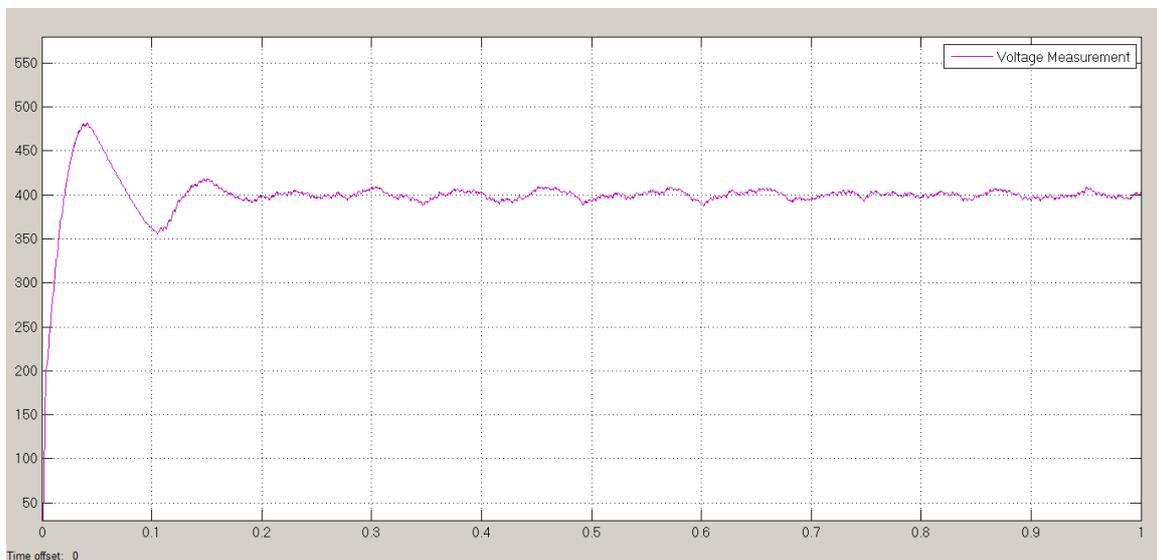


Figure 7 voltage waveform for the values  $K_p=0.009$  and  $K_i=1.5$ .

S.I No.	$K_p$	$K_i$	$V_i$	$V_o$
1	0.009	1.1	24	402.7
2	0.009	1.2	24	406.3
3	0.009	1.3	24	404.3
4	0.009	1.4	24	400.2
5	0.009	1.5	24	404.1

Table showing different output values with varying values of  $K_p$  and  $K_i$ .



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From Figure 7 it is very much clear and can be calculated that the output voltage  $V_O$  is not much stable with  $K_p=0.009$  and  $K_i=1.1, 1.2, 1.3, 1.5$  and the maximum peak overshoot, rise time is also more than the output in Figure 4. The output voltage waveform shown in Figure 4 has less settling time. Hence, we have chosen the values for  $K_p$  and  $K_i$  as in serial number 4 from the table i.e.  $K_p=0.009$  and  $K_i=1.4$ . While the converter specifications were kept same.

## V.CONCLUSION

Here a high step-up boost converter using coupled inductor with proportional integral control is simulated. By the capacitor charged in parallel and discharged in series by the coupled inductor, high step-up voltage gain of 400V is achieved. As the output voltage of the converter with PI Control has minimum overshoot and produces a constant output current shown. These studies could solve many types of problems regardless on stability because as we know that proportional integral controller is an intelligent controller to their appliances.

Further it can be simulated with different types of feedback control like fuzzy logic control, artificial neural network, genetic algorithm and others can be used for advanced tuning and to check the constant output voltage with least ripple and to support different appliances with different voltage ratings.

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## BIOGRAPHY



Saurabh was born in Jharkhand, India on January 15, 1990. He received his B.Tech degree in Electronics and Instrumentation Engineering from Bharath University, Chennai in 2011, and currently he is doing M.Tech degree in Power Electronics and Drives from Jalpaiguri Government Engineering College, Jalpaiguri, West Bengal.



Prof. Pradip Kumar Saha, Professor, Department of Electrical Engineering, Jalpaiguri Government Engineering College, Jalpaiguri, WB -735102. BE (Electrical) from B.E. College, Shibpore. M.Tech (Electrical) Specialization: Machine Drives & Power Electronics from IIT- Kharagpur, PhD from University of North Bengal. FIE, MISTE, Certified Energy Auditor.



Prof. Gautam Kumar Panda, Professor and Head, Department of Electrical Engineering, Jalpaiguri Government Engineering College, Jalpaiguri, WB -735102. BE (Electrical) from J.G.E.C., Jalpaiguri, M.E.E (Electrical) Specialization: Electrical Machines & Drives from Jadavpur University, PhD from University of North Bengal, FIE, MISTE, Certified Energy Auditor.