

# DEBRIS FLOW HAZARD ZONATION BY PROBABILISTIC ANALYSIS (MT. WOOMEYON, SEOUL, KOREA)

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**Abstract:** This paper presents the application results of a regional, distributed empirical model: Flow path assessment of gravitational hazards at a Regional scale: (Flow-R) for a catchment on Woomeyon Mountain, Seoul, Korea. This model couples probabilistic and energetic algorithms for assessing of the spreading of flow and maximum runout distance. Flow-R also adopts the Geographic Information Systems (GIS) framework for determining the debris flow susceptibility for the whole mountain. In this paper, susceptibility scenarios have been simulated taking into account different source and propagation parameters. The best-fit values for the minimum plan curvature for initiating debris flow and the travel angle (vertical elevation to horizontal distance ratio) of runout distance were found to be  $-1/100 \text{ m}^{-1}$  and  $13^\circ$ , and the resulting propagation on one of the calibration site was validated using the simplified friction limited model. Based on the results, the use of this model can be considered an important tool for debris flow analysis, especially in areas where related properties of the debris flow are not well defined.

**Keywords:** Flow-R, Woomeyon, GIS, Susceptibility map, Plan curvature, Travel angle, Net efficiency

## I. INTRODUCTION

Physical modelling of debris flows in a wide area is difficult because of the complexity of the phenomenon and the variability of controlling factors. However, it is still necessary to identify the hazard areas by debris flows at regional scale and to describe the threat. This is because, nowadays a number of debris flow events have been occurred at the same time. The Woomeyon mountain debris flow in Seoul is an example for these severe events.

In order to reduce risk posed by debris flows, research identifying the hazard areas by debris flows and describing the threat play an important role. Thus, debris flow susceptibility modelling at regional scale has been a subject of various studies in the last decades (Horton *et al.*, 2008). As a result, there are a number of models adopting both empirical and deterministic approaches for predicting debris flow. However, the process based models of debris flow are difficult to apply because of the complexity of the phenomenon and the variability of controlling factors. These physical variables that control the mechanism of debris flows, also cannot be acquired over wide areas at reasonable cost (Lari *et al.*, 2011). Empirical models offer an alternative, not only general low data availability but also large scale assessment (Kappes *et al.*, 2011).

In this study a coupled susceptibility analysis model using probabilistic and energetic algorithms, Flow-R, was carried out for Mt. Woomeyon area, situated in Seoul. Flow-R (Flow path assessment of gravitational hazards at a Regional scale), developed at the University of Lausanne in Swiss, aims at giving a regional assessment of debris flows susceptibility with minimum data requirement (Horton *et al.*, 2013). This program is based on the Matlab and available free of charge. Because of a paucity of input data which reflect Korean condition, we focus on parametric analyses to calibrate and test the model. The Flow-R model simulation resulted in reasonable estimates of debris flow initiation and spreading distance of reach. It can be found that the Flow-R model is applicable to catchments in mountainous terrain of Korea with limited data availability.

## II. CASE STUDY

### A. Study Area

The study area was Woomeyon Mountain, which is located in Seocho district of Seoul City, South Korea (Fig. 2). It is located at  $37^\circ 27' 23'' - 37^\circ 28' 55''$  N latitude and  $126^\circ 59' 20'' - 127^\circ 01' 28''$  E longitude. The elevation of

Woomyeon Mountain is 293 m above sea level. This area completely encircled by buildings and roads amounts to 5,104,162 m<sup>2</sup> and is predominantly covered by forest, mostly oak trees.

The Mt. Woomyeon range is basically composed of Pre-Cambrian banded biotite gneiss and granitic gneiss as depicted in Fig. 2. The banded biotite gneiss was moderately weathered and has stripes called gneissic banding, which develops under conditions of high temperature and pressure. Because of the gneissic banding, it is clear that the study area has been exposed to extreme shearing.

Sixty percent of the study areas between 50 m and 150 m of elevation, while 67% of the slope angles are between 10 and 25 degrees. Hillslope is mostly toward S and E (about 14%, respectively) and display similar region of convex and concave (Fig. 1). The soil profile can be divided into three main layers (Korean Geotechnical Society, 2011): (1) colluvium layer extends to a maximum depth of 3.0 m from the ground level and the upper part of this layer was formed from previously transported soil. This layer is generally loose material composed of gravel and silty-sand, according to the Unified Soil Classification System (USCS), a heterogeneous, incoherent and permeable soil. (2) A transition zone is composed of mainly a clay layer (depth: 0.2 m to 0.5 m) characterized by the colors taupe and dark brown. It was anticipated that landslides would be generated by conditions in this layer between the colluvium and bedrock. (3) A subsoil of stiff weathered bedrock is followed by a clay layer. This subsoil layer can be considered impervious according to the low hydraulic conductivity indicated by the modelling that follows.

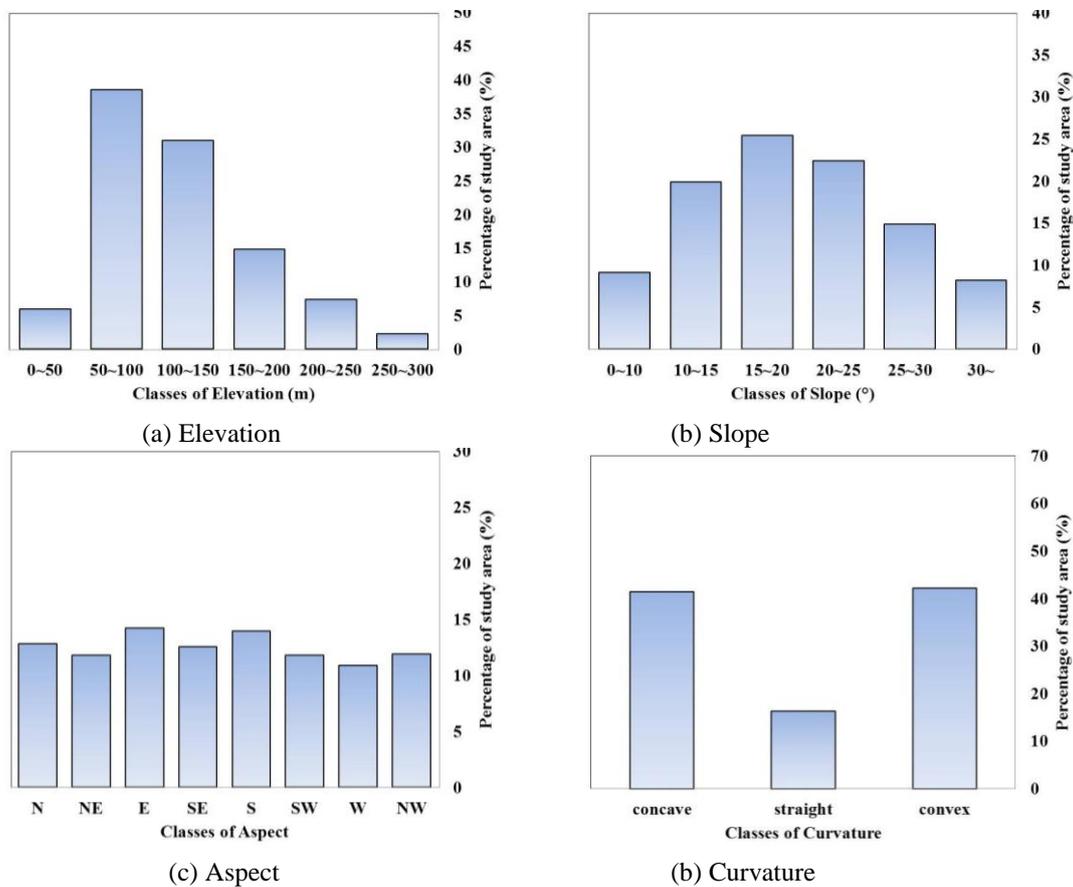


Fig. 1 Classes of topographic parameters in study area (elevation, slope angle, aspect and curvature)

B. Debris Flow Event

In the area of Mt. Woomyeon, a number of catastrophic, debris flow events were triggered by a localized torrential rainfall from July 26 to July 27 in 2011. During severe storms, the failed soil mass rapidly propagated downslope and increased its initial volume through erosion of in-place soils producing a dangerous mobilized volume. These mixtures of debris flowed down the roadways into local communities. Sixteen people were killed and ten buildings were damaged by the debris, leading to economic losses of about US\$15 million. Fig. 2(b and c) depicts the damaged districts (destroyed buildings, inundated areas, and debris flow channels) after the disaster. The average length of debris flows in the study area was about 317.0 m, with an average volume of 269m<sup>3</sup>. The biggest debris flow has a length of 1365 m while the smallest is less than several tens of meters (Korean Society of Civil Engineers and Korean Geotechnical Society, 2012).

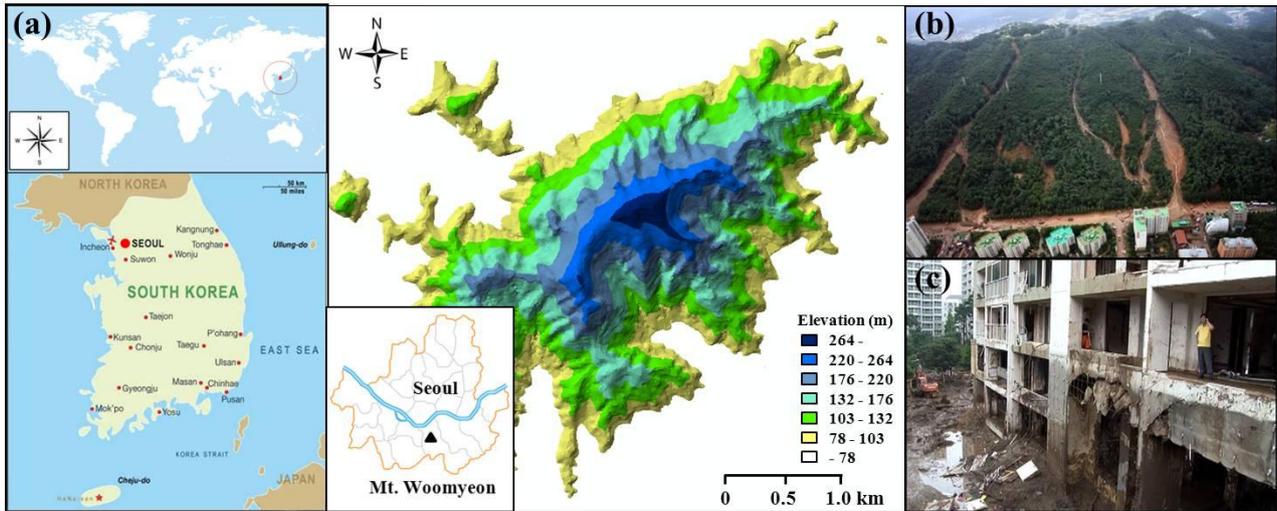


Fig. 2 Location map and debris flow event of Mt. Woomyeon in Korea

### III. THEORETICAL BASIS OF FLOW-R

Application of the model can be divided into two main steps based on a digital elevation model: (1) source areas are first identified by means of geomorphological and userdefined criteria. (2) debris flows are propagated from these sources on the basis of flow direction algorithms and frictional laws.

Fig. 2 depicts above procedure using conceptual diagram. The debris flow volume and mass are not considered since accurate values cannot be easily assessed over a large area. During the motion, significant mass changes occur through erosion and deposition. Because the model is described in detail by Horton *et al.* (2013), only a brief explanation is represented here.

#### A. Identification of Sources

For the identification of possible debris flow source areas; slope, and flow accumulation, as well as plan curvature were used for modelling in each DEM cell. These parameters are related with three critical factors affecting directly or indirectly for the debris flow initiation: sediment availability, water input and slope gradient (Takahashi, 1981; Rickenmann and Zimmermann, 1993). The sediment availability is related to the lithology in a geology map and the upslope contributing area is taken into account for water input because it is the same as precipitation region. The slope angle is a major criterion due to its influence on the shear strength of a soil. Moreover, the plan curvature for detecting gully and land use/cover map are added to increase the detection quality.

##### 1) Slope angle

In the case of slope angle, most debris flows occur in areas with a gradient higher than 15° (Takahashi, 1981; Rickenmann and Zimmermann, 1993). Thus, all cells with slope angle lower than 15° were excluded in this analysis.

##### 2) Upslope area

The upslope contributing area was taken into account as a characteristic of water input because it can represent the amount of water through the cell. The debris flow initiation threshold between slope angle and contributing area were expressed by an empirical relationship based on observations of Rickenmann and Zimmermann (1993) and Heinemann (1998) as shown in Fig. 3. The two equations representing rare events and extreme events respectively are the following (Horton *et al.*, 2013):

$$\begin{cases} \tan\beta_{\text{thres}} = 0.32S_{\text{uca}}^{-0.2}, & \text{if } S_{\text{uca}} < 2.5\text{km}^2 \\ \tan\beta_{\text{thres}} = 0.26, & \text{if } S_{\text{uca}} \geq 2.5\text{km}^2 \end{cases} \quad (1)$$

$$\begin{cases} \tan\beta_{\text{thres}} = 0.31S_{\text{uca}}^{-0.15}, & \text{if } S_{\text{uca}} < 2.5\text{km}^2 \\ \tan\beta_{\text{thres}} = 0.26 & , \text{if } S_{\text{uca}} \geq 2.5\text{km}^2 \end{cases} \quad (2)$$

where  $\tan\beta_{\text{thres}}$  is the slope threshold, and  $S_{\text{uca}}$  is the surface of the upslope contributing area. In this analysis, an “extreme fitting” curve was selected among two curves, as it covers a higher possibility for debris flow initiation than rare fitting. All cells above this threshold were considered from possible sources area according to empirical observations.

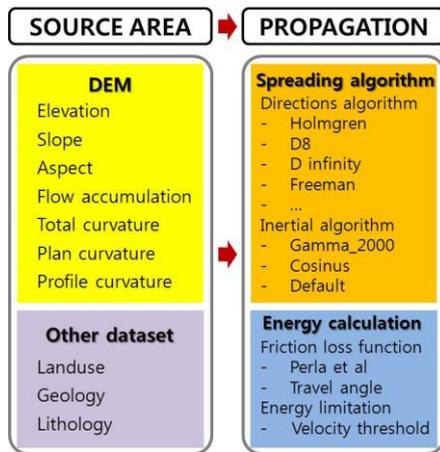


Fig. 3 Conceptual diagram of Flow-R

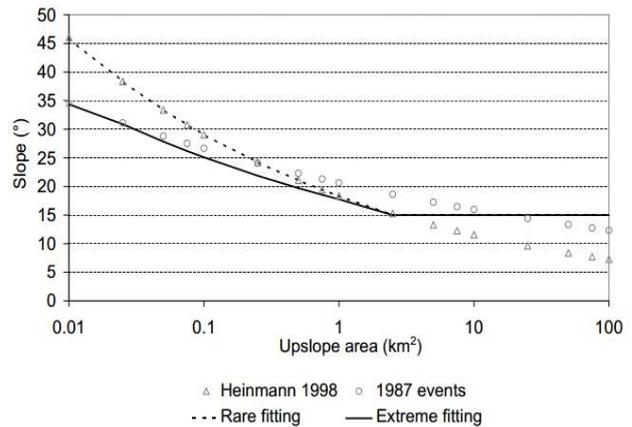


Fig. 4 Slopes and upslope area thresholds for debris flow initiation for rare and extreme events

### 3) Plan curvature

Debris flow sources are identified in the region where curvature is concave (Delmonaco *et al.*, 2003; Wiczorek *et al.*, 1997). The plan curvature which is perpendicular to the steepest slope provides recognition of gullies that are considered as debris flow potential sources. Fisher *et al.* (2012) considered values of  $-0.5/100 \text{ m}^{-1}$  to  $-1.5/100 \text{ m}^{-1}$  for accuracy in Norway. This value, also, was set to  $-2/100 \text{ m}^{-1}$  according to the experience of Horton *et al.* (2008) in the Canton de Vaud, Switzerland. However, there is no admitted threshold in the literature. This threshold is expected to be different according to the location, type of debris flows as well as accuracy of DEM (Horton *et al.*, 2013).

### 4) Other datasets

Any other dataset based on GIS can also be considered, such as geological maps or land use maps to remove inaccurate source areas. For example, outcropping or sub-outcropping rocks in geology map and built-up areas in land use map should be excluded from possible debris flow source area. In the simulations carried out in this study, these maps did not consider because there is no debris flow in non-occurring condition.

Finally all classified input parameters were integrated in order to determine the possible location of debris flow source. If a pixel is determined as possible debris flow source and never excluded are assigned as sources at least once, this cell can become debris flow source.

## B. Runout and Spreading Modelling

In a second step, the maximum runout propagation is calculated both starting from the previously determined sources and using two types of functions: flow direction and runout distance algorithms.

### 1) Flow direction

Several algorithms for the representation of flow directions, using rectangular grid digital elevation models, are available: D8 (O’Callaghan and Mark, 1984), D infinity algorithm (Tarboton, 1997), multiple direction method (Quinn *et al.*, 1991) and its modification (Holmgren, 1994). In the D8 and D infinity methods, water flows down one or two cells by partitioning the flow between the two cells nearest to the steepest downward slope direction. On the other hand, the multiple direction method and the modified multiple flow direction methods spreading the flow on a percentage basis over several neighbouring downslope pixels are more realistic. The modified multiple flow direction method was used

because it is physically more realistic. The modified multiple flowdirection method after Holmgren (1994) is represented by the following equation:

$$p_i^{fd} = \frac{(\tan \beta_i)^x}{\sum_{j=1}^8 (\tan \beta_j)^x} \text{ for all } \tan \beta > 0 \quad (3)$$

where  $i, j$  are the flow directions,  $p_i^{fd}$  is the susceptibility proportion in direction  $i$ ,  $\tan \beta_i$  is the slope gradient between the central cell and the cell in direction  $i$ , and  $x$  is the variable exponent. In case of  $x = 1$ , the spreading is similar to the multiple flow direction by Quinn *et al.* (1991), and the divergence is reduced as  $x$  increases. Also, it can be a single flow direction when  $x \rightarrow \infty$ . This factor can control degree of spreading and thus allows us to reproduce a wide range of other flow accumulations; e.g., debris flows, rock falls, avalanches, and floods (Kappes *et al.*, 2012). For a debris flow case, Holmgren (1994) proposed a range of  $x$  between 4 and 6 in the Eq. (3). In this analysis, 4 was selected for the wide spread modelling as proposed by Claessens *et al.* (2005) and Horton *et al.* (2008).

In addition to the influence of slope, the effect of the flow inertia is considered for flow direction. Table 1 presents three implementations of the persistence. Based on the result of Gamma (2000), persistence weight for each cell was implemented in this study. For  $0^\circ$ , a persistence weight of 1 is assigned, for  $45^\circ$  0.8, for  $90^\circ$  0.4, for  $135^\circ$  and for  $180^\circ$  0 as depicted in Table 1. Thus the final probabilities are the combination of the spreading and the persistence.

$$p_i = \frac{p_i^{fd} p_i^p}{\sum_{j=1}^8 p_j^{fd} p_j^p} p_o \quad (4)$$

where  $i, j$  are the flow directions,  $p_i$  is the susceptibility value in direction  $i$ ,  $p_i^{fd}$  is the flow proportion according to the flow direction algorithm,  $p_i^p$  is the flow proportion according to the persistence, and  $p_o$  is the previously determined susceptibility value of the central cell.

## 2) Propagation

The maximum distance reached by the debris flow is computed with basic energy based calculations without considering source masses since they are mostly unknown in regional analyses. Thus, the soil mass that cannot be reached has a kinetic energy set to zero. This approach does not aim to represent the accurate physical processes, but to obtain a realistic result. The kinetic energy  $E_{kin}^i$  at the time step  $i$  is obtained by the following formula:

$$E_{kin}^i = E_{kin}^0 + \Delta E_{pot}^i - E_f^i \quad (5)$$

where  $E_{kin}^i$  is the kinetic energy of the cell in direction  $i$ ,  $E_{kin}^0$  is the kinetic energy of the central cell,  $\Delta E_{pot}^i$  is the change in potential energy to the cell in direction  $i$ , and  $E_f^i$  is the energy lost in friction to the cell in direction  $i$ .

This energy based spreading algorithm controls spreading area of debris mass using energy balance, a friction loss function and maximum velocity threshold. First, the friction loss  $E_f^i$  can be assessed by two algorithms: the two parameters friction model by Perla *et al.* (1980) and the simplified friction limited model (hereafter, SFLM). Both methods can result in similar propagation areas, depending on the parameters (Jaboyedoff *et al.*, 2011). Because the formal model was described in detail by Perla *et al.* (1980), only a brief explanation is given here. This model was developed for avalanches, but has also been used for debris flows (Zimmermann *et al.*, 1997). It is based on non-linear friction law using mass to drag ratio and friction coefficient. The difficulty is to know these values, because they change along the flow path. However, the SFLM method is more preferred since it has only 1 variable. This model estimates the maximum possible runout distance using a minimum travel angle, also named a reach angle. Fig. 4 represents the basic concept of SFLM. The travel angle is computed by connecting a line between source area and the most distant point reached by the debris flow along its path:

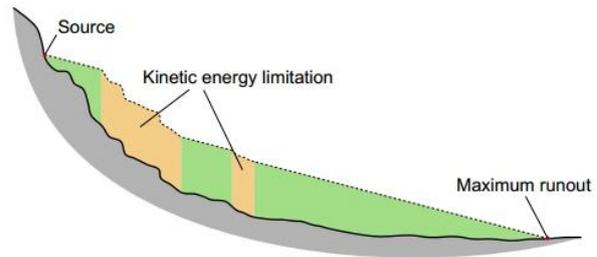
$$E_f^i = g \Delta x \tan \phi \quad (6)$$

where  $E_f^i$  is the energy lost in friction from the central cell to the cell in direction  $i$ ,  $\Delta x$  is the increment of horizontal displacement,  $\tan \phi$  the gradient of the energy line, and  $g$  the acceleration due to gravity. Reviewing a number of cases in the world, the angle of travel has a range of  $5^\circ \sim 15^\circ$ . Lower angle implies the result of the worst case analysis or wide spreading.

Second, the kinetic energy is limited by an upper velocity threshold for estimating realistic kinetic energy. The 15 m/s is reasonable for debris flow based on the observed maximum velocity of the overlapping flows in Swiss (Horton, 2008; Blahut *et al.*, 2010).

**Table 1** Weighting factor of the persistence function

	$w_0$	$w_{45}$	$w_{90}$	$w_{135}$	$w_{180}$
Proportional	1.0	0.8	0.4	0.0	0.0
Cosines	1.0	0.7	0.0	0.0	0.0
Gamma (2000)	1.5	1.0	1.0	1.0	0.0



**Fig. 5** Illustration of travel angle and velocity limitation of SFLM

#### IV. APPLICATION OF THE MODEL

In the simulations carried out in this study, different plan curvature and travel angle were considered for calibration. The plan curvature is perpendicular to the steepest slope and provides source of debris flow. By identifying gullies, it allows refining the delineation of the source areas. Second, travel angle is the angle of the line connecting the source area to the mass deposit reached by the debris flow. This concept enables the estimation of the deposit if the source area is known. This angle corresponds to the propagation distance and it is called *Fahr-böschung* (Heim, 1932).

The most important dataset is the DEM. For Mt. Woomyeon, topographic analyses for elevation, slope angle, flow accumulation and curvature were calculated from 1:5000 maps developed by the National Geographic Information Institute. The ArcGIS was used to create grids with 10 m cells and to quantify the aforementioned information above for each cell of the DEM.

Horton *et al.* (2013) conducted Flow-R analysis using 1 m, 2 m, 5 m, 10 m, 25 m, and 50 m resolution DEM to verify sensitivity between grid sizes and analysis results. As a result, they pointed out that 10m DEM resolution satisfies reasonable propagation extent with Holmgren's algorithm. Moreover, lower cell sizes do not bring significant information, even though they certainly lead to an increase of computation time. These are consistent with the results of Zhang and Montgomery (1994) and Quinn *et al.* (1995) who concluded that 10 m grid size is recommended for landslide assessment as well as flow direction algorithm.

Any other datasets based on GIS such as geological maps or land use maps are not considered due to homogeneous soil and land use condition.

##### A. Source Thresholds

As for the case of Mt. Woomyeon, the standard geomorphological data; e.g., slope, flow accumulation and curvature were integrated with the following parameters:

- Elevation: no criteria
- Slope threshold: 15°
- Flow accumulation – slope relationship: extreme threshold
- Plan curvature:  $-1/100 \sim -2/100 \text{ m}^{-1}$  (the range used in this study)

**Table 2** Implemented plan curvature in the assessment of the source area

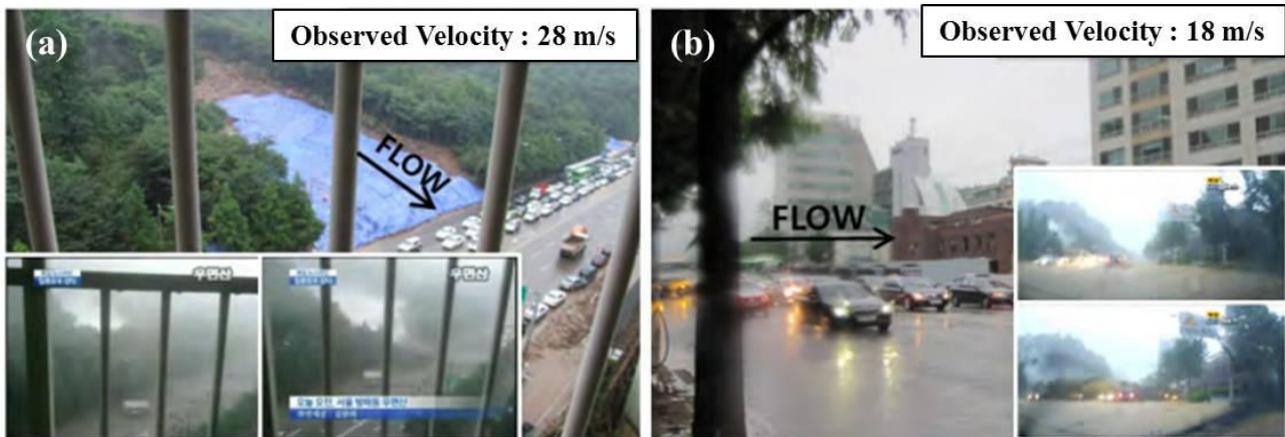
Researches	Plan curvature ( $\text{m}^{-1}$ )	Grid size	Country
Horton et al. (2008)	-2/100	10m	Swiss
Blahut et al. (2010)	-1/100	20m	
Fisher et al. (2012)	-0.5/100 ~ -1.5/100	10m	Norway
Ellen et al. (1997)	-1/100	30m	USA

There is no threshold value for plan curvature in the literature. Plan curvature is inferred to different values according to the several conditions as mentioned before. To know the plan curvature input value in Korea roughly, we searched plan curvature in this study with reference values listed in Table 2. On the basis of this scarce literature, a plan curvature range of  $-0.1/100 \sim -2/100 \text{ m}^{-1}$  was assumed.

**B. Propagation Thresholds**

Propagation parameters were taken from the literature in case of well supported by both physical and empirical backgrounds.

- Directions algorithm: Holmgren’s modified algorithm, with an exponent of 4
- Inertial algorithm: Gamma(2000)
- Velocity threshold : 28 m/s
- The friction loss function: SFLM, with a travel angle of  $5^\circ \sim 15^\circ$  (the range used in this study)



**Fig. 6** CCTV and Black box video at Mt. Woomyeon event (a) Raemian apartment, (b) Sindonga apartment

The maximum velocity threshold of debris flow mass used in this study was deduced from observed velocity of the event. Among many debris flows, Fig. 6(a) and (b) show the observed velocity of the event for Raemian and Sindonga apartment basin, respectively. Based on the CCTV and Black box in the damaged car at that time, the maximum velocity of the Mt. Woomyeon debris flow was estimated to be 28 m/s. This velocity is higher than other countries’ values since there was much water on slope just before the event. It means that the concentration of debris mass was very low.

As for the plan curvature, various travel angles has been chosen according to the characteristics of debris flow for each region. Table 3 represents angle of the line connecting the source area to the most remote deposit reached by the debris flow in literature. Reviewing a number of cases in the world, the minimum angle of travel has a range of  $5^\circ \sim 15^\circ$ . For the Korean condition, a travel angle was assumed from the list summarized in Table 3. Afterwards, Flow-R analysis was performed using Woomyeon case study for verification.

**Table 3** Implemented travel angle in the assessment of the spreading

Researches	Travel angle	Remarks	Country
Haeberli (1983)	$\sim 11^\circ$	Glacier floods	Swiss
Rickenmann and Zimmermann (1993)	$\sim 11^\circ$		Swiss
Zimmermann et al. (1999)	$7^\circ \sim 11^\circ$	Grained distribution	Swiss
Prochaska et al. (2008)	$6.5^\circ \sim$		USA, Canada, Australia
Bathurst et al. (1997)	$11^\circ$		Japan
Huggel et al. (2002)	$\sim 11^\circ$		Canada and Swiss
Lari et al. (2011)	$5^\circ \sim 15^\circ$	Water content	Italy

V. RESULTS AND DISCUSSION

At regional scale within GIS environment, the analysis of spatial probability estimation was performed for the debris flow susceptibility. This kind of approach requires the comparison of debris flow that happened in the past with a set of environmental factors, in order to predict areas of debris flow initiation that have similar conditions, using heuristic or statistical methods (Van Westen *et al.*, 2005). To calibrate the parameters of debris flow, the documents of debris flow mapping using satellite images and aerial photographs taken after event, as well as field survey report by the Korean Society of Civil Engineers were analyzed. Afterwards, the parameters calibration was performed for two different parameters: 1) Plan curvature for debris flow source area, 2) Travel angle for debris flow propagation distance in keeping other conditions same. The rest conditions in this study were same.

The plan curvature and travel angle for values ranging from  $-0.5/100\text{ m}^{-1}$  to  $-2/100\text{ m}^{-1}$  for the identification of initiation and from  $5^\circ$  to  $15^\circ$  for spreading of debris flow were used in Flow-R. The results were following. The results of the debris flow source map with different plan curvature thresholds are presented in Fig. 7. In case of  $-1/100\text{ m}^{-1}$  in Fig. 7(b), A good correlation between the modelling results and the field observations was found in this study. High probability of debris flow was classified using color code with red. However, Fig. 7(a) with plan curvature threshold of  $-2/100\text{ m}^{-1}$  shows some failure prediction cases. The blue circles depicting debris flow non-occurrence in Fig. 7 is because of the plan curvature threshold. This indicates that an assumed minimum plan curvature threshold of  $-1/100\text{ m}^{-1}$  would be sufficient to identify the source areas threatened by debris flows in the Mt. Woomyeon.

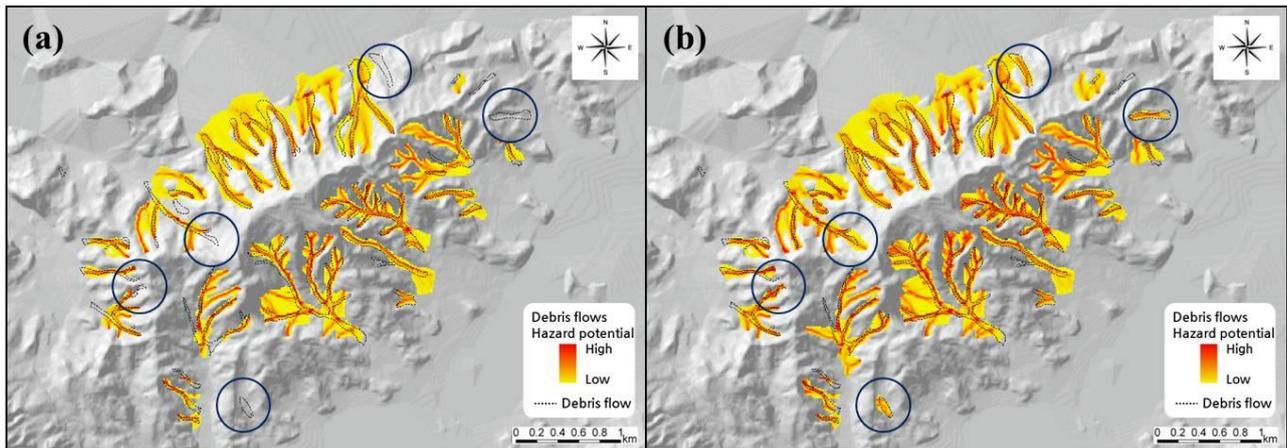


Fig. 7 Spreading results for Mt. Woomyeon (a) Threshold for planar curvature set to  $-2/100\text{ m}^{-1}$  (b) Threshold for planar curvature set to  $-1/100\text{ m}^{-1}$

In terms of reach angle, Flow-R simulation was conducted. As a result, the particular difference was observed in the predicted debris flow scarp distribution according to different travel angle as shown in Fig. 8 and Fig. 9. For the three other cases, clear trend was visible. The case (a) in both Fig. 8 and Fig. 9 with travel angle  $15^\circ$  shows short runout distance than debris flow mapping. It does not completely contain the area affected by the mapped debris flow events. Thus, different from what actually happen, there is no socio-economic impact to local communities. In contrast, case (c) over-estimates the hazard area due to high value of horizontal distance. As a comparison with other travel angles, the reach of propagation with angle  $13^\circ$  reasonably estimates debris flow hazard area. That is, the calibrated reach angle of  $13^\circ$  showed a good adjustment of the past event.

In Korea, the maximum probable travel angle of debris flows was suggested by Choi and Paik (2012). They observed the former events (238 debris flow cases) including Mt. Woomyeon in Korea, and suggested the angle of  $13^\circ$  (H/L is 4.5) to a representative angle. This is well coincided with the simulated result. Besides, Kim and Hwang (2011) proposed that a mean travel angle in Inje, Korea is  $11.5^\circ$  (H/L is 4.93).

Although the approach presented here has its limitations and cannot reflect the exact physical behavior, it can provide preliminary assessment over wide areas. Fig. 8 and 9 show debris flow hazard region predicted by the model. A good coherence between the simulated propagation area and actual damage area was observed in the region where major debris flow events occurred. In the framework of susceptibility mapping, the resulting areas are often larger than the observed events on the field. This is the reason why the predicted area is larger than observed debris flow scarp.



**Fig. 8** Debris flow hazard zone in the Raemian and Sindonga apartment basin (a) travel angle = 15°, (b) travel angle = 13°, (c) travel angle = 11°



**Fig. 9** Debris flow hazard zone in the Hyungchon village basin (a) travel angle = 15°, (b) travel angle = 13°, (c) travel angle = 11°

## VI. CONCLUSION

This paper presented a probabilistic approach to assess the susceptibility of debris flow in a mountainous region in Seoul, Korea. Especially, we concentrated on parametric studies to take into account different source and propagation related parameters. This presented approach of debris flow hazard analysis, associating detection of the source areas with a simple assessment of the debris flow spreading, provide encouraging results for consequent hazard and risk studies.

From the calibration phase, the following source and runout characteristics were selected: plan curvature  $-1/100 m^{-1}$ ; the maximum runout (shadow) angle  $13^\circ$ . These debris flow characteristic properties reasonably estimated the initiation zone and runoff distance for the Mt. Woomyeon debris flow hazard based on GIS framework at regional scale.

In conclusion, Flow-R successfully simulates the observed debris flow propagation path for Mt. Woomyeon case. Slight incoherence in the predicted travel length of spread area is due to non-consideration of rheology characteristics of flow. However, the debris flow propagations simulated with Flow-R adequately follow the channels, even if some over-estimated area created incoherent paths. That is, observations of previous events in the same region were satisfyingly reproduced during the validation procedures. Debris flow modelling using this kind of approach has following advantages: (1) it provides susceptibility map over a large area, (2) it allows very fast computation, and (3) it gives useful results with minimum dataset. Further research can be carried out to improve the Flow-R model by adopting appropriate region based parameters.

## ACKNOWLEDGEMENT

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