



International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

Design of Solid State Transformer

B. Dheeraj Reddy¹, Dr. Sarat Kumar Sahoo²

UG Student [EEE], School of Electrical Engineering, VIT University, Vellore, Tamilnadu, India¹

Associate Professor, School of Electrical Engineering, VIT University, Vellore, Tamilnadu, India²

ABSTRACT: Transformers are designed so as to minimize weight and cost based on three presumptions: the power supply is with a sine wave, the frequency is fixed, and the voltage not to exceed a prescribed maximum limit. Fastidious approach in designing the transformer based on these assumptions is not entailed, then again proper consideration is required if the assumptions are amended. Given this as beginning, an efficient and cost-effective design has to be resolved. In order to reduce the emission of greenhouse gas and replace the limited energy sources like coal or oil, the number of renewable energy sources is constantly growing. All these points led to have a best solution which was the reason for evolution of Solid State Transformer. This paper presents the constructional details of a 100 VA, 100 Hz and 200 VA, 50 Hz transformer and compares the results to claim the best design.

KEYWORDS: Solid State Transformer (SST), Power Electronic Devices, SST Topology, Smart Grid.

I. INTRODUCTION

The conventional “behemoth” transformers, highly efficient and reliable, suffer certain demerits: sensitive to harmonics, no power factor improvement, poor performance under dc-offset load unbalances, voltage drop under load, no protection from system disruptions and overloads. A transformer equipped with Power Electronic Devices can respond to control signals and eliminate the problems linked to conventional transformer as mentioned. The solid state transformer endeavours to replace the traditional 50 Hz transformer by means of high frequency isolated AC/AC solid state conversion techniques. SST, because of the power electronics circuit, can be operated at any frequency. Due to high-frequency modulation; the volume and weight of SSTs can be much smaller than those of conventional 50 Hz transformers and also allows higher utilization of the magnetic core. Solid state transformers possess lower physical contours than traditional 50 Hz transformers and provide active control of power flow. However, they are not as simple as traditional 50 Hz transformers because of the presence of power electronic converters. But this is made up by the ancillary services provided by the power electronic devices like allows two way power flow, actively change power characteristics such as voltage and frequency levels, improves power quality (reactive power compensation and harmonic filtering), provides efficient routing of electricity based on communication between utility provider & end users and other transformers in the network.

In this paper, it proposes to review the available literature on Conventional transformer design and various models of SSTs and selects the best one for optimum efficiency. Then by adopting suitable methodology an efficient transformer is designed.

There are two methodologies that can be adopted in designing the new transformer. Let the base be a 100 VA, 50 Hz transformer on which both the approaches can be employed.

- 1) The aforementioned base transformer can be operated at 100 Hz which augments the power transfer capability to 200 VA (i.e.; almost doubles) with increase in frequency whereas the core size and weight remain unchanged.
- 2) A new design procedure can be worked out with frequency fixed at 100 Hz, unlike base frequency of 50 Hz, and power capacity at 100 VA. The size and weight of this new transformer design will be reduced as compared to the base transformer.

Case 1 outranks the other because in this case the original base transformer, initially working at 50 Hz, can itself be operated at 100 Hz for double the power capacity instead of designing a new transformer which saves time and money. Only precaution to be taken is that the transformer, because of magnetostriction due to high frequency, will vibrate and

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

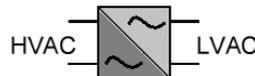
(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

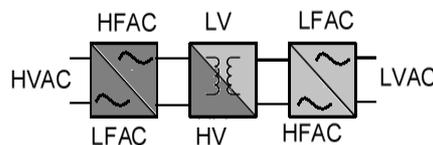
produce a humming noise which can be negated by tightening the core bolts. Also, a growing demand for electric power craves for parallel operation of transformers; so a new transformer has to be installed every time power demand intensifies. With the case-1 transformer, as mentioned, the power demand can be compensated without buying a new transformer.

II. SST TOPOLOGIES

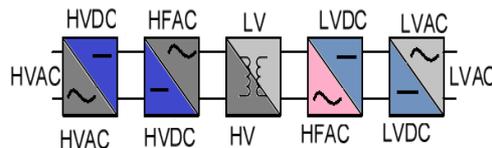
i. Direct AC to AC Converter



ii. SST without a DC link



iii. SST with a DC link (Three-stage SST)



The three stage topology offers some advantages over the other two, such as [1]; reduced size due to a high frequency transformer, power factor improvement is possible, multi-level converter topologies can be applied to get high voltage levels (e.g., 11 and 22 kV). It is the three stage topology which is most prevalent now and various potentials of the power electronic circuit involved, like reduced switch topology, are being studied and developed for better proficiency.

III. LOSSES INVOLVED

For a given voltage and number of turns, increasing the frequency allows for decreasing the cross-sectional area of the core without bringing the core into saturation. The advantage of running an electrical system at 100 to 400 Hz rather than 50 Hz is that the power supplies are smaller and lighter. But this reduction in weight comes at the cost of power electronic devices. As we know the iron loss consists of two components; the hysteresis and the eddy current components [2].

Hysteresis loss (W_h) $\propto B_m^{1.6} f \propto (V/f)^{1.6} f \propto f^{-0.6}$ (with constant voltage)
 $\propto 0.096$ for 50 Hz and 0.06 for 100 Hz.

So, whenever frequency is increased, the flux density (B_m) reduces and hence there is some reduction (around 40%) in W_h .

Eddy Current loss (W_e) $\propto B_m^2 f^2 \propto (V/f)^2 f^2$,
i.e., W_e is constant for any frequency if voltage is constant.

Now calculating for 1 Tesla;

at 50 Hz: $W_h + W_e \propto 1^{1.6} * 50 + 1^2 * 50^2 \propto 2550$ and

At 100 Hz: $W_h + W_e \propto 0.5^{1.6} * 100 + 0.5^2 * 100^2 \propto 2533$

i.e.; Total iron loss reduces by 0.67%. $(= \frac{100 * (2550 - 2533)}{2553})$.

Increase in copper loss due to skin effect is not significant up to certain level.

As per the available literature; Diameter of wire which see 10% rise in resistance (in mm)

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

$$d = 200/\sqrt{f} = 28 \text{ mm for } 50 \text{ Hz} = 20 \text{ mm for } 100 \text{ Hz} \text{ and } = 10 \text{ mm for } 400 \text{ Hz.}$$

It is well known that the skin effect is more significant when the frequency is above 400 Hz (this is the reason aircrafts use 400 Hz supply) whereas our study is restricted to 100 Hz only. Hence the total losses are almost constant for the double the frequency. The interconnecting devices would enable full control of magnitude and direction of real and reactive power flow and could replace the archaic uncontrollable, voluminous and heavy, line frequency transformers.

IV. DESIGN OF TRANSFORMER

Based on the standard formulae [3]-[5] and practical considerations, an excel spreadsheet has been generated. This should expedite the process of designing transformer with ease and accuracy for several other ratings.

A. The design of the 100 VA, 440/220 V transformer has been tested with the spreadsheet and the results are found to be similar to the calculated values as per the standard text books with an appreciable error of 1% in VA rating and efficiency. The developed excel spreadsheet is shown (table.1)

B. Estimation of Output rating with same core for double the frequency:

$$Q = 2.22 * B_m * f * A_i * A_w * K_w * J * 10^{-6}$$

$$= 2.22 * 1 * 100 * 0.001216 * 0.000768 * 0.3 * 3.5 * 10^{-6} = 218 \text{ VA}$$

The data has been fed to the developed spreadsheet and found that the output is doubled and concurs with the calculated value (table.2).

C. The design of the 200 VA, 50 Hz (table.3) :

D. Comparison of different designs : Shown in table-4.

E. Results : In spite of increase in the frequency, the core losses are reduced which is already mentioned earlier. The transformer's no load current has been measured (hardware) and the results corroborate the above statement. Using a supply source of 440V, 50Hz the following currents are measured :

Frequency	50Hz	100Hz
No load current	80mA	65mA

F. Winding Arrangement : Fig 1 shows the Winding arrangement of 100 VA, 50 Hz transformer.

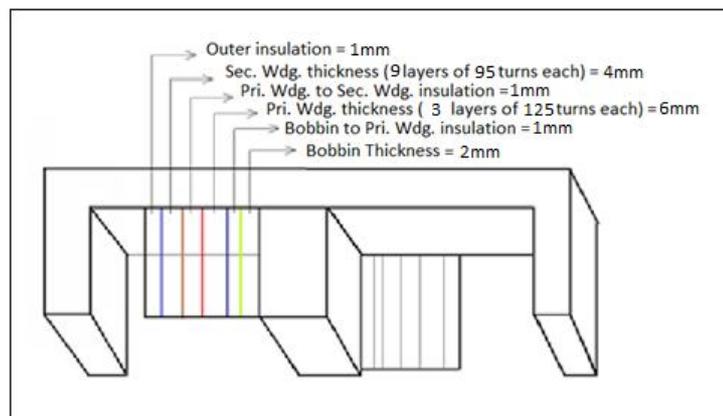


Fig 1 Winding arrangement of 100 VA, 50 Hz Transformer

Fig 2 shows the Winding arrangement of 200 VA, 50 Hz

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

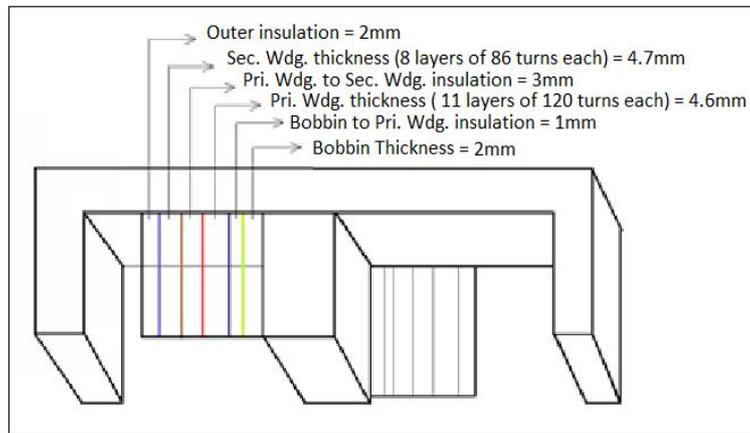


Fig 2 Winding arrangement of 200 VA, 50 Hz

V. CONCLUSION

From the comparison table, case-3 transformer offers slightly less efficiency and modest core loss. Whereas, case-2 transformer proposes the minimum voltage drop, better efficiency and least unit rate. Not to forget, the supplementary pros of using power electronics in the circuit in the SST paradigm. Also, the reduced no load or core losses substantiates the superior qualities of SST. Contemplating various parameters involved in the design and the practical considerations taken into account; case-2 i.e. 100 VA, 100 Hz transformer possess the attributes of a transformer that would fit perfectly in the future smart grid.

ACKNOWLEDGEMENT

The authors would like to thank the School of Electrical Engineering (SELECT), VIT University, Vellore, Tamil Nadu for their continuous guidance and encouragement to carry out this work.

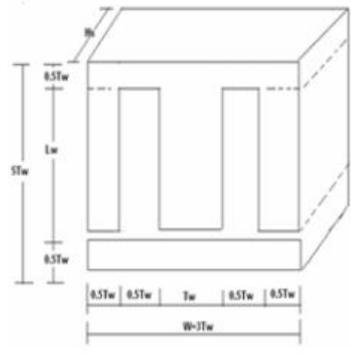
REFERENCES

1. Xu She; Alex Q. Huang; Rolando Burgo, "Review of Solid-State Transformer Technologies and Their Application in Power Distribution Systems" IEEE 2168-6777- 2013.
2. Indrajit Dasgupta, "Design of Transformers", McGraw Hill Education (India) Private Limited, New Delhi, India.
3. Sawhney A.K., "Electrical Machine Design", DhanpatRai publishers, India.
4. M.G. Say, "Performance and Design of Alternating Current Machines", CBS Publishers & Distributors, Delhi.
5. H.M.Rai, "Principles of Electrical Machine Design", Satyaprakashan Publishers, New Delhi.

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

Table 1: Transformer Design Calculations (100 VA, 50 Hz) - Single Phase Shell type						
1	Input (Data to be Given):					
	Core Center leg (Tongue) width (Tw)-mm	32		Flux Density(Bm)-Wb/m ² or Tesla	1	
	Core Stack height (Hs)-mm	38		Window Fill factor(Kw)	0.30	
	Specific Iron Loss @ 1T, 50Hz - W/Kg	1		Iron Density(g _i)-g/cc	7.7	
	Current Density(J)-A/mm ²	3.5		Copper Density(g _c)-g/cc	8.93	
	Primary Volts - (V ₁)	440		Prices (INR/Kg)		
	Sec. no-load Volts- (V _{2o})	231		Iron	120	
	Frequency(f) - Hz	50		Copper	600	
	Copper Resistivity at 20 ^o C- Ω.mm ² /m	0.017				
	2	Output data:				
Area of Core gross section(Agi) -mm ²		1216		Window area (Aw) -mm ²	768	Area of Copper (Ac) - mm ²
Turns per Volt (Tpv)		3.70	Average(or Mean) turn length(Lmt)- mm	190.3		
Primary turns (N1)		1630	Pri. Cond. Length-L1	310	Pri.Conductor size (a ₁)-mm ²	0.07
Secondary turns (N2)		856	Sec. Cond. Length-L2	163	Sec.Conductor size(a ₂)-mm ²	0.13
Input power (S1) - VA		109	Pri. Current- I ₁ (A)	0.25	Iron loss (Wi)- W	1.80
Power loss -%		10.04	Sec. Current - I ₂ (A)	0.47	Copper loss(Wc)- W	9.13
Voltage drop -%		4.19			Total loss -W	11
Sec. Volts on Full Load (V ₂)		221				
Iron weight(Gi) - kg		1.80	Copper weight (Gc)-kg	0.39	Total Weight (Iron+Copper) - Kg	2.19
Cost (Iron+Copper)+Misc.-INR		789	Unit Rate-INR/VA	8.05	Weight of Ins, Bobbin, Clamps etc.-Kg	0.11
Output power (S2) - VA		98	Efficiency (%)	89.96	Gross weight -Kg	2.30

6.

Table-1

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

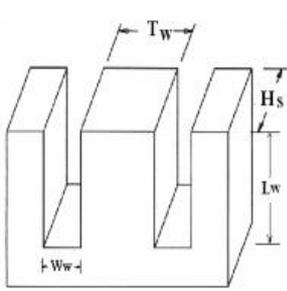
Table 2: Transformer Design Calculations (100 Hz With Same Core-200 VA) - Single Phase Shell type							
1	Input(Data to be Given):						
Core Center leg (Tongue) width (Tw)-mm	32			Flux Density(Bm)-Wb/m ² or Tesla	1		
Core Stack height (Hs)-mm	38			Window Fill factor(Kw)	0.30		
Specific Iron Loss@1T,50Hz - W/Kg	1.0			Iron Density(g _i) - g/cc	7.7		
Current Density(J)-A/mm ²	3.5			Copper Density(g _c) - g/cc	8.93		
Primary Voltage (V ₁) - V	440			Prices (INR/Kg)			
Sec. no-load Voltage (V _{2o}) - V	225			Iron	120		
Frequency(f) - Hz	100			Copper	600		
Copper Resistivity at 20 ^o C-Ω.mm ² /m	0.017						
2	Output data:						
Area of Core gross section(Ag _i) - mm ²	1216			Window area (Aw) -mm ²	768	Area of Copper (Ac) - mm ²	230.40
Turns per Volt (Tpv)	1.85	Average (or Mean) turn length(Lmt)- mm	165.1				
Primary turns (N ₁)	815	Pri. Cond. Length-L1	135	Pri.Conductor size (a ₁)-mm ²	0.14		
Secondary turns (N ₂)	417	Sec. Cond. Length-L2	69	Sec.Conductor size(a ₂)-mm ²	0.28		
Input power (S₁) - VA	218	Pri. Current- I ₁ (A)	0.49	Iron loss (Wi)- W	1.80		
Power loss - %	4.47	Sec. Current - I ₂ (A)	0.97	Copper loss(Wc)- W	7.92		
Voltage drop - %	1.82			Total loss -W	10		
Sec. Voltage on Full Load (V ₂)	221						
Iron weight(G _i)- kg	1.80	Copper weight (G _c)-kg	0.34	Total Weight(Iron + Copper)-Kg	2.14		
Cost (Iron + Copper)+Misc.-INR	734	Unit Rate-INR/VA	3.53	Weight of Ins, Bobbin, Clamps etc.-Kg	0.11		
Output power (S₂) - VA	208	Efficiency (%)	95.53	Gross weight -Kg	2.24		

Table-2

International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

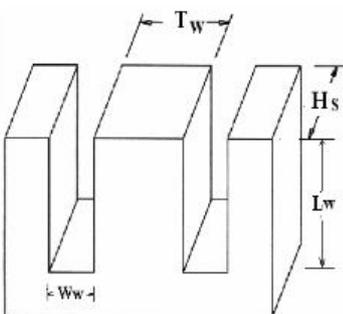
Table 3: Transformer Design Calculations (200 VA, 50 Hz) - Single Phase Shell type					
1 Input (Data to be Given):					
Core Center leg (Tongue) width (Tw)-mm	38			Flux Density(Bm)-Wb/m ² or Tesla	1
Core Stack height (Hs)-mm	40			Window Fill factor(Kw)	0.33
Specific Iron Loss @ 1T, 50Hz - W/Kg	1			Iron Density(g _i)(g/cc)	7.7
Current Density(J)-A/mm ²	3.5			Copper Density(g _c)(g/cc)	8.93
Primary Volts - (V ₁)	440			Prices (INR/Kg)	
Sec. no-load Volts- (V _{2o})	230			Iron	120
Frequency(f) - Hz	50			Copper	600
Copper Resistivity at 20 ^o C- Ω.mm ² /m	0.017				
2 Output data:					
Area of Core gross section(Agi) - mm ²	1520	Window area (Aw) -mm ²	1083	Area of Copper (Ac) - mm ²	357.39
Turns per Volt (Tpv)	2.96	Average(or Mean) turn length(Lmt)- mm	215.7		
Primary turns (N1)	1304	Pri. Cond. Length-L1	281	Pri.Conductor size (a ₁)-mm ²	0.14
Secondary turns (N2)	682	Sec. Cond. Length-L2	147	Sec.Conductor size(a ₂)-mm ²	0.26
Input power (S1) - VA	211	Pri. Current- I ₁ (A)	0.48	Iron loss (Wi)- W	2.7
Power loss -%	5.07	Sec. Current - I ₂ (A)	0.92	Copper loss(Wc)- W	8
Voltage drop -%	3.80			Total loss -W	11
Sec. Volts on Full Load (V ₂)	221				
Iron weight(Gi)- kg	2.67	Copper weight (Gc)-kg	0.69	Total Weight (Iron + Copper) -Kg	3.36
Cost (Iron + Copper)+Misc.-INR	973	Unit Rate-INR/VA	4.86	Weight of Ins, Bobbin, Clamps etc.-Kg	0.17
Output power (S2) - VA	200	Efficiency (%)	94.93	Gross weight -Kg	3.5

Table-3



International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 1, January 2015

Table 4: Comparison of parameters with different frequencies and Cores							
S. No.	Frequency (Hz)	50	100	% Deviation	50	% Deviation	Remarks (Compare Case -2 and Case-3)
Case :	1= Base	2= Same Core (double output)	3=To get same output as 100 Hz with 50 Hz				
1	Primary Volts (V1)	440	440	0	440	0	
2	Sec. no-load Volts- (V _{2o})	230	225	-2.5974	230	-0.43	Good with case-3
3	Primary turns (N1)	1630	815	-50	1304	-20	Excellent with case-2
4	Secondary turns(N2)	856	417	-51.299	682	-20.35	Best with case-2
5	Area of Core gross section(Agi)-mm ²	1216	1216	0	1520	25	Good with case-2
6	Area of Copper (Ac) -mm ²	230.4	230.4	0	357.4	55.12	Best with case-2
7	Iron weight(Gi)- kg	1.80	1.80	0	2.67	48.44	Best with case-2
8	Copper weight (Gc)-kg	0.39	0.34	-13.209	0.69	75.86	Good with case-2
9	Total Weight-Kg	2.19	2.14	-2.362	3.36	53.34	Good with case-2
10	Unit Rate-INR/VA	8.05	3.53	-56.10	4.86	-39.62	Good with case-2
11	Input power (S1)- VA	109	218	100	211	93.90	Good with case-2
12	Iron loss -W	1.80	1.80	0	2.67	48.44	Good with case-2
13	Copper loss- W	9.13	7.92	-13.209	8.03	-12.08	Good with case-2
14	Total loss- W	11	10	-11	11	-2.12	Good with case-2
15	Voltage drop -%	4.19	1.82	-56.605	3.80	-9.31	Excellent with case-2
16	Output power (S2)- VA	98	208	112	200	104.44	Good with case-2
17	Efficiency (%)	89.96	95.53	6.20	94.93	5.53	Good with case-2

Table-4