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Implementation of Cascaded H Bridge Inverter Using Space Vector PWM

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ABSTRACT: The modulation and control strategies plays vital role to minimize THD in Multilevel inverter .The modulation technique includes Sinusoidal Pulse Width Modulation (SPWM), Selective harmonic Elimination and Space Vector Pulse Width Modulation (SVPWM).Multilevel inverters has tremendous application in the area of high-power and medium-voltage energy control. In this paper simulation of SVPWM is performed for cascaded H bridge inverter . Simulation of three level, five level and seven level cascaded H bridge inverter with Space vector PWM has been carried out. Implementation and simulation of SVPWM inverter are presented to realize the validity of the SVPWM technique.

KEYWORDS: Multilevel Inverter, Pulse Width Modulation, Space vector pulse Width Modulation, Sinusoidal Pulse Width Modulation.

I.INTRODUCTION

Numerous industrial applications require higher power apparatus in recent years. Some medium voltage motor drives and utility applications require medium voltage and megawatt power level. A multilevel power converter structure has been introduced as an alternative in high power and medium voltage situations Subsequently, several multilevel converter topologies have been developed. A multilevel converter not only achieves high power ratings but also enables the use of renewable energy sources. The advantages of three-level Inverter topology over conventional two-level topology are 1)The voltage across the switches is only one half of the DC source voltage 2)The switching frequency can be reduced for the same switching losses 3)The higher output current harmonics are reduced by the same switching frequency.

The cascaded H bridge inverter has the advantage of a reduction in switch count and more effective utilization of the natural switching speed and voltage-blocking characteristics of the different types of power electronic devices that are used. The most common strategy used for the cascaded H bridge inverter is the phase-shifted carrier PWM, which provide improved harmonic performance when each single-phase inverter is controlled using three-level modulation [1].Although the cascaded H bridge inverter has an inherent self-balancing capability, because of the losses in circuit component and limited controller resolution, a slight voltage imbalance can occur. The simple control block with PI regulator to adjust the trigger angle and to ensure zero steady-state error between the reference dc voltage and the dc-bus voltage can ensure the dc voltage balance , reactive and harmonic compensations [2].An automatic voltage balance can be achieved by supplying voltage to cascaded H bridge inverter by using a high-frequency link which generates all the isolated dc supplies. Therefore low and constant THD at all operating ranges can be obtained [3]. The cascaded H bridge multilevel inverter can be used for high power applications with novel MMC-based frequency changing conversion scheme[4].The modulation methods used in multilevel inverters can be classified according to switching



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frequency. The existing system used Space vector PWM contol with less number of sectors whereas in proposed system number of sectors used is more to the THD



Fig 1 Schematic diagram of a proposed Cascaded H-bridge inverter with Space Vector PWM control.

II. PULSE WIDTH MODULATION

The dc input to the inverter is "chopped" by switching devices in the inverter (bipolar transistors, thyristors, Mosfet, IGBT ...etc). The amplitude and harmonic contents of the ac waveform are controlled by controlling the duty cycle of the switches. This is the basic of the pulse width modulation (PWM) techniques. There are several PWM techniques each has itsown advantages and also disadvantages. The basicPWM techniques are described briefly in thefollowing subsections. The considered PWMtechniques are:

- 1) Sinusoidal PWM
- 2) Hysteresis band current control
- 3) Space-Vector PWM
- A. Sinusoidal PWM

The most popular PWM approach is the sinusoidalPWM. In this method a triangular (carrier) wave iscompared to a sinusoidal wave of the desired fundamental frequency and the relative levels of the two signals are used to determine the pulse widths and control the switching of devices in each phaseleg of the inverter.



(b) states of switches of phase a

Fig. 2 Principle of three phase sinusoidal PWM.



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B. Hysteresis-band current control

In hysteresis-band current control the actual current tracks the form of command current within a hysteresis band. In this approach the reference current wave is compared to the actual current wave thus producing the current error .When the current error exceeds a predefined hysteresis band, the upper switch in the half-bridge is turned off and the lower switch is turned on. As the current error goes below the hysteresis band, the opposite switching takes place. The principle of hysteresis band current control is illustrated in Fig. 3.Hysteresis-band current control is very popularbecause it is simple to implement, has fast transientresponse, direct limiting of device peak current and practical insensitivity to machine parameters because of the elimination of any additional currentcontrollers. However, PWM frequency is not fixedwhich results in non-optimal harmonic ripple inmachine current.



Fig. 3 Principle of hysteresis band current control.

C. Space vector pulse width modulation

Space vector PWM refers to a special switchingscheme of the six power semiconductor switches of a three phase power converter.Space vectorPWM (SVPWM) has become a popular PWMtechnique for three-phase voltagesource inverters inapplications such as control of induction andpermanent magnet synchronous motors. Thementioned drawbacks of the sinusoidal PWM andhysteresis-band current control are reduced usingthis technique. Instead of using a separate modulatorfor each of the three phases the complex reference voltage vectorsprocessed as a whole. Therefore, the interactionbetween the three motor phases is considered. It hasbeen shown, that SVPWM generates less harmonic distortion in both output voltage and current applied to the phases of an ac motor and provides a more efficient use of the supply voltage in comparison with sinusoidal modulation techniques.



Fig. 4 Non-zero vectors and zeroVectors forming a hexagon .



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III SOFTWARE IMPLEMENTATION OF SPACE VECTOR PWM

Space vector PWM can be implemented by the following steps: 1) Determine, and $angle(Vd, Vq, Vref, \alpha)$.

2) Determine the time duration T 1T2T0

3) Determine the switching time of each MOSFET

1)The Vd, Vq, Vref, and angle (α) can be determined from following steps

The voltage vectors on the alpha and beta axis can then be described as:

$\begin{bmatrix} Vd\\ Vq \end{bmatrix} = \frac{2}{3} \begin{bmatrix} 1\\ 0 \end{bmatrix}$	$-\frac{1}{2}$ $\frac{\sqrt{3}}{2}$	$ -\frac{1}{2} \\ -\frac{\sqrt{3}}{2} \begin{bmatrix} Van \\ Vbn \\ Vcn \end{bmatrix} $		(1)
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The magnitude and angle of the reference vector is:

$$|Vref| = \sqrt{Vd^2 + Vq^2} \qquad (2)$$

$$\alpha = \tan^{-1} \left[\frac{Vq}{Vd} \right] \qquad (3)$$

2) Determine time duration T₁, T₂, T₀

The switching time duration for T_1, T_2, T_0 is given below

$$T_{1} = T_{s} \cdot \left| \frac{Vref}{Vdc} \right| \cdot \frac{\sin\left(\frac{\pi}{3} - \alpha\right)}{\sin\left(\frac{\pi}{3}\right)}$$
(4)

$$T_2 = T_s \cdot \left| \frac{Vref}{Vdc} \right| \cdot \frac{\sin(\alpha)}{\sin(\frac{\pi}{3})}$$
(5)

And,
$$T_0 = Ts - (T_1 + T_2)$$
 -----(6)

3) Determine the switching time of each MOSFET

Sector	Upper Switches	Lower Switches
	$S_1 = T_1 + T_2 + T_0/2$	
1	$S_3 = T_2 + T_0/2$	$S_4 = T_0/2$
	$S_5 = T_0/2$	$S_6 = T_1 + T_0/2$
		$S_2 = T_1 + T_2 + T_0/2$
	$S_1 = T_1 + T_0/2$	$S_4 = T_2 + T_0/2$
2	$S_3 = T_1 + T_2 + T_0/2$	$S_6 = T_0/2$
	$S_5 = T_0/2$	$S_2 = T_1 + T_2 + T_0/2$
	$S_1 = T_0/2$	$S_4 = T_1 + T_2 + T_0/2$
3	$S_3 = T_1 + T_2 + T_0/2$	$S_6 = T_0/2$

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	$S_5 = T_2 + T_0/2$	$S_2 = T_1 + T_0/2$
	$S_1 = T_0/2$	$S_4 = T_1 + T_2 + T_0/2$
4	$S_3 = T_1 + T_0/2$	$S_6 = T_2 + T_0/2$
	$S_5 = T_1 + T_2 + T_0/2$	$S_2 = T_0/2$
	$S_1 = T_2 + T_0/2$	$S_4 = T_1 + T_0/2$
5	$S_3 = T_0/2$	$S_6 = T_1 + T_2 + T_0/2$
	$S_5 = T_1 + T_2 + T_0/2$	$S_2 = T_0/2$
	$S_1 = T_1 + T_2 + T_0/2$	$S_4 = T_0/2$
6	$S_3 = T_0/2$	$S_6 = T_1 + T_2 + T_0/2$
	$S_5 = T_1 + T_0/2$	$S_2 = T_2 + T_0/2$

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IV RESULTS AND DISCUSSIONS

The main aim of any modulation technique is to obtain variable output having maximum fundamental component with minimum harmonics. The objective of Pulse Width Modulation techniques is enhancement of fundamental output voltage and reduction of harmonic content in Three Phase Voltage Source Inverters. In this paper Space Vector PWM techniques for different levels are compared in terms of Total Harmonic Distortion (THD).

Parameters of Multilevel inverter

A Simulation of SVPWM

Space vector PWM is an advanced technique used for variable frequency drive applications. It utilizes dc bus voltage more effectively and generates less THD in the Three Phase Cascaded H bridge inverter. SVPWM utilize a chaotic changing switching frequency to spread the harmonics continuously to a wide band area so that the peak harmonics can be reduced greatly. Simulation has been carried out by varying the modulation index between 0 and 1. Finally performance of SVPWM is improved in fivel level with 12 sector when compared to three level inverter with 6 sector.

The Block Diagram of Space Vector Pulse width modulated inverter fed RL load is shown in Figure 5.

In SVPWM methods, the voltage reference is provided using a revolving reference vector. In this case magnitude and frequency of the fundamental component in the line side are controlled by the magnitude and frequency, respectively, of the reference voltage vector. Space vector modulation utilizes dc bus voltage more efficiently and generates less harmonic distortion in a three phase voltage source inverter and multi level inverter.



Fig 5.Simulink block diagram of three level Cascaded H Bridge Inverter.



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The Block Diagram of five level Cascaded H bridge inverter using Space Vector Pulse width modulation is shown in Figure-12



Fig 6.Simulink block diagram of three level Cascaded H Bridge Inverter.

Parameters	Value
Dc link voltage	400V
Switching period	100µs
Resistance	75Ω
Inductance	2.652mH

The above block diagram shows that software implementation of cascaded H bridge inverter with Space Vector PWM.The Waveform of three level and five level cascaded H bridge inverter is shown in the fig 8and fig 9

Comparative analysis of cascaded H bridge inverter						
	Cascaded H	sectors	THD			
	bridge inverter					
	3 level	6	26.44%			
	5 level	12	14.38%			
	7 level	24	13.56%			

 TABLE II

 Comparative analysis of cascaded H bridge inverter

Fig 7.Simulink block diagram of SVPWM

The phase voltage of Three level cascaded H bridge inverter is shown in the fig 8



Fig 8. Phase voltage of Three level Cascaded H bridge Inverter



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The phase voltage of Five level cascaded H bridge inverter is shown in the fig 9



Fig 9. Phase voltage of Five level Cascaded H bridge Inverter

The FFT analysis of three and five level cascaded H bridge inverter withSVPWM is shown in the fig 10, fig 11. From which we five level multilevel inverter produces THD of 14.38% when compared to three level of 26.44%



Fig 12 .FFT analysis for seven level cascaded H bridge Inverter

V CONCLUSIONS

Space vector Modulation Technique has become the most popular and important PWM technique for Three Phase Voltage Source Inverters for the control of AC Induction, Brushless DC, Switched Reluctance and Permanent Magnet Synchronous Motors. In this paper first comparative analysis of Space Vector PWM with different sectors is carried out. The Simulation study reveals that SVPWM gives 13.58% THD for seven level and 26.4 % for three level cascaded H bridge inverterenhanced fundamental output with better quality i.e. lesser THD compared to SVPWM.SVPWM are implemented in MATLAB/SIMULINK software. SVPWM utilize a changing carrier frequency to spread the harmonics continuously to a wideband area so that the peak harmonics are reduced



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