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OPTIMIZED APPROACH FOR PROVISIONING VPN IN THE HOSE MODEL WITH QOS

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Abstract: Virtual private networks provide an encrypted connection between a user's distributed sites over a public network. Existing studies on quality of service deals with bandwidth in hose model. In this paper an Enhanced Hose model is used to specify the bandwidth and link utilization between the end points. We introduce a VPN tree algorithm (KDSVT) that is capable of computing all possible cost and link utilization of VPN Tree. Based on this algorithm we introduce a novel algorithm that can achieve a cost optimized and link utilization VPN tree (KCDVT) with low average computational complexity.

INTRODUCTION

A virtual private network (VPN) is a private data network that makes use of the public Internet [1] to maintain privacy through the use of IP tunneling technology and network security protocols. VPNs can be regarded as a replacement of the expensive private leased lines. The main purpose of a VPN is to provide a company secure communication among multiple sites through the shared Internet. More detailed descriptions of VPNs can be found in [2] and [12]. To support a VPN, a service provider has to allocate predetermined paths to connect among customer sites. As customers may want to have bandwidth guaranteed, enough bandwidth has to be reserved on these paths. Therefore, finding appropriate paths and appropriate bandwidth reservation while minimizing the total bandwidth used becomes an important problem to service providers.

Two popular models for specifying customer bandwidth requirements have been proposed. They are known as the pipe model and the hose model. In the pipe model, customers are required to specify the bandwidth they need among each pair of VPN endpoints. In other words, a customer has to know the traffic between each pair of sites in advance and inform the service provider. This model is not very flexible since a customer may not be able to predict the communication patterns between VPN endpoints. Another disadvantage of this model is that the resources reserved for a pair of VPN endpoints cannot be allocated to other traffic flows. Thus, the utilization of internet resources becomes very inefficient. The hose model was proposed by Duffield et al. to solve the problems of the pipe model [3]. In the hose model, VPN customers just need to specify the incoming and outgoing traffic volume of each VPN endpoint (known as ingress bandwidth and egress bandwidth) instead of between every pair of VPN endpoints. The ingress bandwidth of an endpoint is the capacity required for aggregating the incoming traffic to the endpoint from other endpoints. The egress bandwidth is the capacity required for aggregating the outgoing traffic from the endpoint into the network. In other words, ingress bandwidth specifies the maximum amount of traffic an

endpoint would receive per time unit while egress bandwidth specifies the maximum amount of traffic an endpoint would send out per time unit. Detailed examples showing the differences between the pipe model and the hose model can be found in [5].

ANALYSIS OF DATA

The Enhanced Hose Model:

We model the network as a graph G = (V, E) where V is the set of nodes and E is the set of bidirectional links connecting the nodes. Each link (i, j) is associated with two QoS metrics - the bandwidth capacity Lij and the delay Dij. The delay value of a path is defined as the sum of the delay values of all links along the path. The VPN specification in the hose model includes [7]: (1) A subset of the nodes $P \subseteq V$ corresponding to the VPN endpoints, and (2) for each node i ϵ P, the associated ingress and egress bandwidths Bi ⁱⁿ and Bi^{out} respectively. Note that the terms "ingress" and "egress" are taken with respect to the VPN endpoints. This model can be enhanced to include a delay requirement in two ways: (1) Associate a delay requirement Di with each node i, which specifies the maximum delay from this node to every other node in the VPN, or (2) Group applications that use the VPN into different delay classes characterized by their end-to-end delay requirements that must hold between every pair of end points. We adopt the latter approach in this paper.

Implementing Enhanced Hose Model:

We use |P| source-based trees to realize the hoses, one tree per hose. For a given source based tree T rooted at the VPN endpoint i, we denote by Tv the connected component of T containing node v when link (u, v) is deleted from the tree. In this case, the traffic passing through link (u, v) can only originate from i to the other endpoints in Tv. The traffic that i can send is bounded by Bi ^{out}, and the traffic that Tv can receive cannot exceed $\sum B j^{in}$, $j \in p \cap TV$. Thus the bandwidth reserved for link (u, v) of T is given by CT (u, v) = min (Bi ^{out}, B $\sum B j^{in}$, $j \in p \cap TV$ }. Since we are interested in minimizing the total bandwidth reserved for tree T, the problem of computing the optimal source-based tree for endpoint i can be expressed as follows:

Optimal Delay-Constrained Source-Based Tree Problem: Given a set of VPN endpoints P with their associated ingress and egress bandwidths and the delay requirement D, compute a source-based tree T rooted at endpoint i whose leaves are the other VPN endpoints. The objective is to minimize CT while satisfying the delay requirement, delay $(i, j) \leq D$.

Theorem 1: The Optimal Delay-Constrained Source-Based Tree Problem is NP-hard.

RELATED WORKS

System Model and Problem Statement:

System Model:

We adopt some of the notations developed in [5]. A network is modeled as a graph G = (V, E), where V is the set of nodes and E is the set of bidirectional links among the nodes in V. (i, j) and (j, i) are considered as two distinct links. Each link (i, j) is associated with capacity Lij. It is possible that Lij \neq Lji. In the hose model, each VPN specification consists of a set of VPN endpoints P V and the ingress and egress bandwidths of each of the VPN endpoints. Ingress bandwidth is the maximum amount of traffic a VPN endpoint would receive, while egress bandwidth is the maximum amount of traffic the VPN endpoint would send. For a node i ϵ . P, the hose ingress and egress bandwidths are both Bi, since we consider the case of symmetric ingress and egress bandwidths only.



Figure 1: Example network

We use a tree to connect VPN endpoints. Formally, a tree T = (V_T,E_T) is a sub graph of G where $P \subseteq V_T \subseteq V$ and $E_T \subseteq E$. Enough bandwidth has to be reserved on the links of the tree to support the VPN. To facilitate our discussion, we define $T_i^{(i,j)}$ and $T_j^{(i,j)}$, meaning the connected components of T containing nodes I and j respectively after removing (i, j) from T. Refer to the tree in Figure 1 in which dark nodes represent VPN endpoints and light nodes represent other network nodes, $T_2^{(2,5)}$ stands for the connected component that is made up of nodes 5 to 8. We denote the set of VPN endpoints on Ti ^(i,j) and $T_j^{(i,j)}$ as $P_i^{(i,j)}$ respectively. For example, in the tree in Figure 1, $P_2^{(2,5)} = \{1, 3, 4\}$ and $P_5^{(2,5)} = \{7, 8\}$.

We now explain how much bandwidth is needed to be reserved on link (i, j) on T. Link (i, j) has to support the traffic going from $T_i^{(i,j)}$ to $T_j^{(i,j)}$. In other words, it should support the traffic from VPN endpoint a to VPN endpoint b

amount of traffic that would go through link (i, j) is min $\{\sum a \in P_i^{(i,j)} | B_{a,j}, \sum_{b \in P_j} {}^{(i,j)} B_b\}$ and this is the bandwidth needed to be reserved on (i, j). We denote this value as CT (i, j). As the ingress and egress bandwidths are symmetric, CT(i, j) = CT(j, i). Refer to the tree in Figure 1 in which the number next to each VPN endpoint represents its ingress or egress bandwidth (B1 = 3, B3 = 5, B4 = 4, B7 = 3, B8 = 6), to find CT (5, 6) = CT (6, 5), we first remove the edge (5, 6)from the tree and then compare the following two values: sum of ingress or egress bandwidths of VPN endpoints on the left of node 5 (3 + 5 + 4 = 12) and sum of ingress or egress bandwidths of VPN endpoints on the right of node 6 (3 + 6 = 9) and pick up the smaller of the two (9). We define the utilization of link (i, j), HT (i, j), to be CT (i, j) / Lij. Refer to the tree in Figure 1 where all edges are of capacity 10, HT (5, 6) = 9/10 = 0.9. We further define HT to be the utilization of the most utilized link on the tree, that is, HT $= \max \{ HT(i, j) | (i, j) \in E_T \}.$

PROBLEM STATEMENT

We now formally define the VPN routing problem. Given a graph G, a set of VPN endpoints P, and B_i for each i ε P. Compute a VPN tree T that connects all nodes in P with the following properties:

- a. HT $(i, j) \leq 1$
- b. CT is mini mum among all possible trees.
- c. Tree also satisfies the delay requirement.

The first property simply says that the capacity constraint should not be violated. This property makes the problem NP-hard [5]. The second property means that we would like to find an optimal tree that requires the least amount of bandwidth among all possible trees.

PROPOSED METHOD

<u>Algorithm:</u>

Input: Network as graph

Output: Least-delay Least-cost optimized

VPN-Tree [V-number of VPN nodes

k- Number of shortest path to find between each pair]

Step 1: For each pair of vertices find the k-Shortest delay path if available. Totally v-1 set of shortest path available

i.e.) $\{k1\}$ $\{k2\}$... $\{kv-1\}$ set of shortest path and each set having k-paths.

Step 2:

Generate a new tree by taking union of paths taking one from each set of shortest paths. It produces $k1 \times K2 \times ... \text{ kv-} 1$ number of induced trees. It may contain cycle.

Paths = \emptyset

 $Path_set = \emptyset$

For each node s ε N

For each node d ϵ N – {s}

Find the shortest path SP between s and d with Dijkstra algorithm

Path_set = Path_set U {SP} n = 1While (n < K) and (Path_set $\neq \emptyset$)

Take the first path p of Path_set Path_set = Path_set - {p}

Paths = Paths U $\{p\}$

Search L(p) While $(L(p) \neq \emptyset)$ and (n < K)Take the less-cost link l of L(p) $L(p) = L(p) - \{1\}$ Remove the link l of the network and search the new shortest path SP' between s and d (Dijkstra) If SP' is found Path set = Path set U {**SP**'} n = (n + 1)End If Reinsert 1 in the network End While End While

End For **Step 3:**

For each tree perform the cycle detection algorithm to detect the cycle. If cycle is found delete the tree from the list. **Step 4:**

Compute the cost required for each tree.

Step 5:

The tree with the low cost is selected as the Least-delay Least-cost optimized VPN tree.

Step 6: End

KDSVT Algorithm

K-shortest path algorithm (KSP) Input: source node (s) and destination node (d) Output: k-shortest path between node s and t End For

Figure 2: K-shortest path algorithm

KDSVT algorithm computes the K-delay satisfied VPN tree. The algorithm finds a k-delay satisfied path between source vertexes, which is a VPN endpoint, to all other VPN Endpoints.

Consider there are N VPN Endpoints in the network, KSDVT algorithm find N k-delay satisfied paths. Then a tree is constructed by taking one path from each set of paths. If cycle is detected it may be removed by using spanning tree algorithm. In total it generates k ^N VPN Tree. It gives sufficiently large collection of VPN Tree that makes easier for selecting the VPN tree that optimize the cost in terms of bandwidth.

KCDVT Algorithm:

KCDVT algorithm applies the ingress-egress bandwidth measurement algorithm on all the VPN Trees generated by the KDSVT algorithm. The bandwidth measurement in hose model is as specified in the System model description. The tree which having low bandwidth requirement is selected as the final VPN tree that satisfies delay and bandwidth requirement. It can find a cost optimized and delay satisfied VPN tree (KCDVT) with low average computational complexity. Its computational complexity increases with k. We can minimize its computational complexity by adaptively minimizing k.

INTERMEDIATE RESULT

To measure how effective our KCDVT Algorithm is, we conduct simulations. We generate two different sizes of

topology for testing. For each size, we generate 1000 random topologies based on the WAXMAN model. For each topology, |P| VPN endpoints are randomly picked up. Two different network topologies were used to compare the different provisioning algorithms. The Waxman topology consists of 50 nodes as shown in Figure 3. All the links are bidirectional. A subset of the nodes in the network acts as the ingress–egress pairs. In the Waxman topology, four ingress–egress pairs are considered, which are (0, 12), (4, 8), (3, 1), and (4, 14). The second topology by inserting additional links to increase the connectivity. This topology, called Barabasi topology (BA), consists of 50 nodes and is presented in Figure 4.



Figure 3: Waxman Model: Nodes-50



Figure 4: Barabasi Model: Nodes-50

PERFORMANCE EVALUATION

The cost and link utilization of the VPN tree that satisfies the bandwidth generated by the KCDVT algorithm. The cost of the KCDVT is less than BFS algorithm and the link utilization of KCDVT is more than BFS algorithm. The cost is increasing in proportion with the number of nodes.



Figure 5.1 VPN cost



Figure: 5.2 VPN link utilization

CONCLUSION

In this paper, novel algorithms for provisioning VPNs in the hose model are designed. KCDVT connected VPN endpoints using a tree structure and attempted to optimize the total bandwidth reserved on edges of the VPN tree that satisfies the delay requirement. The algorithm showed that even for the simple scenario in which network links are assumed to have infinite capacity, the general problem of computing the optimal VPN tree is NP-hard. However, for the special case when the ingress and egress bandwidths for each VPN endpoint are equal, KCDVT proposed algorithm for computing the optimal tree. In future there are still a number of issues relating to hose-model VPNs. For example: (1) the problem of fitting failure restoration mechanisms into KCDVT (2) Provisioning for the Asymmetric VPNs.

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