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EMBEDDED DESIGN of TEMPERATURE CONTROLLER USING PIC 16F876A for INDUSTRIES and LABORATORIES

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ABSTRACT: This paper describes a design of an embedded system for temperature controller in a industries and laboratories. The system senses the temperature from the source particularly high temperature source and after signal conditioning; signal is given to the microcontroller. The microcontroller used is PIC 16F876A, which drives the relay for making system ON-Off. The paper describes the controlling action incorporated in the hardware to control the system.

Keywords: Temperature control, RTD, Thermocouple, Signal conditioning, PIC16F876A,

I. INTRODUCTION

Process control is an efficient expression of improving the operation of a process, the productivity of a plant and the quality of products [1]. Nowadays the demand for accurate temperature control has conquered many of the industrial domains such as process heat, altimetry industries where the temperature of plant instruments and process is maintained. To fulfill such a demand, one should promote suitable control strategies. In the past extensively research has been made with respect to temperature control for different types of processes. In this paper the authors designs a PIC microcontroller based temperature control system for casting process. The system was designed with PIC 16F876A microcontroller and implemented. The authors propose the design architecture for furnace temperature measurement and control. The study implies design techniques and control strategies based on PIC controller. Microcontrollers are more reliable as well as efficient [2]. Use of microcontroller in embedded design has not only been increased but brought are revolutionary change. At the same time competitive pressure require manufactures to expand their product functionality and provide differentiation while maintaining or reducing the cost [3].

II. RELATED WORK

In [4] Authors describes that in industries it is very essential to monitor and control temperature accurately, the efficient solution for this problem is to develop a data logger. Earlier it was done manually using the thermometer and manometer. Since 1990 another development in data logging took place as people to begin to create PC based data logging system. In [5] the author describes a single chip embedded temperature controller design Programmed in a single programmable system on chip: mixed array logic consist of analog, digital and digital communication block within in it. The compact design permits the user to select any type of control function through its virtual instrument program. This design can be directly connected to PCs .In [6] author describes web based Distributed measurement and control with programmable 1- wire Digital Temperature sensor DS18B20,an embedded system is used as field processing unit. With application mode of B/S. a remote temperature measurement and control system is designed by embedded web.

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III. MOTIVATION

The purpose of the proposed work is its simplicity, and low cost and industrial and laboratories demand. Such a design is effectively decrease the direct involvement of human being in a industries, particularly in steel industries high temperature environment, chemical laboratories and thus in turn can save power which is the main feature of this work.

IV. EXPERIMENTAL SET UP

The block diagram of the experiment is shown in fig.1. The hardware and software description of an embedded design for temperature controller are described below:

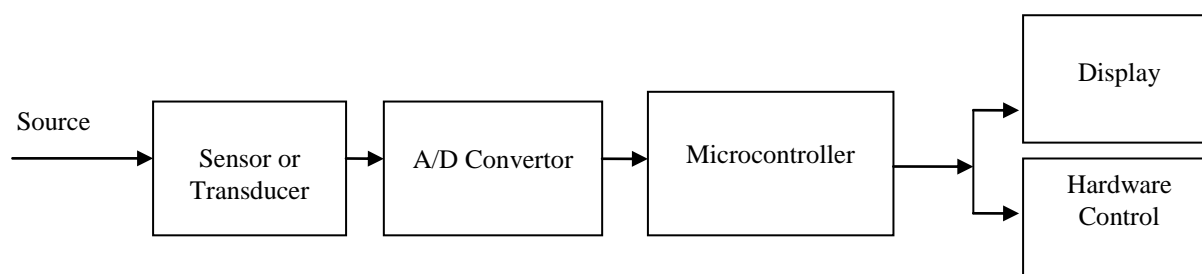


Fig. 1 Block Diagram of System

The figure above shows the basic block diagram of the temperature controller system using PIC 16F876A microcontroller. The power supply for the circuit is regulated by IC 7805, 7812, 7819 and LM317 and supplied to different parts of the unit. The temperature sensor used in the system is Pt-100 RTD. The microcontroller PIC16F876a has in built A/D convertor, which read the temperature from the sensor. The signal conditioning circuit used in the system for proper processing of the signal before it was given to microcontroller. The temperature data is compared with the set temperature and processed inside the microcontroller as per the program and it generate the signal which makes the relay ON or OFF.

The set up can be effectively use in industries and laboratories for measuring and controlling the temperature, The function of each section of the circuit are explained in the following sections;

A. Hardware description

The whole circuit of the experiment is divided into following section:

1) *Power supply*: The regulated power supply section is designed and fabricated with full wave bridge rectifier using voltage regulator IC 7805, 7812, 7912, and LM317, which provides a constant voltage of 5v, 12v, -12v, and +2.5v respectively. These voltages are given to different unit of the system.

2) *Pt-100 Resistance Temperature Detector (RTD)*: RTDs are sensor used to measure temperature correlating the resistance of RTD element with temperature. The RTD element is made from pure material, typically platinum, nickel or copper. The element material has a predictable change in resistance as the temperature changes. It is this predictable change that is used to determine Temperature [7] [8]. Platinum is the best metal for RTD's, because it follows a very linear resistance temperature relationship and it follows $R \propto T$ relationship in a highly repeatable manner over a wide temperature range. It measures the temperature over the range of -272.5°C to 761.78°C . Pure platinum has temperature coefficient of resistance (α) and its value is $0.00385\Omega/\Omega/^{\circ}\text{C}$ in the 0 to 100°C range [9]. The advantages of using platinum RTD is its high accuracy, low drift, wide operating range and stability for precision applications.

3) *Signal Conditioning Circuit*: The system design focuses on circuit solution that uses platinum RTDs. The linearity of the RTD will be presented along with standard formulas that is use to improve the off-the-shelf linearity of the element.

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4) *RTD Current Excitation Circuit:* For best linearity, the RTD sensing element requires a stable current reference for excitation. This is implemented in a way shown in fig.2. In this circuit a voltage reference along with two operational amplifiers are used to generate a floating 1 mA current.

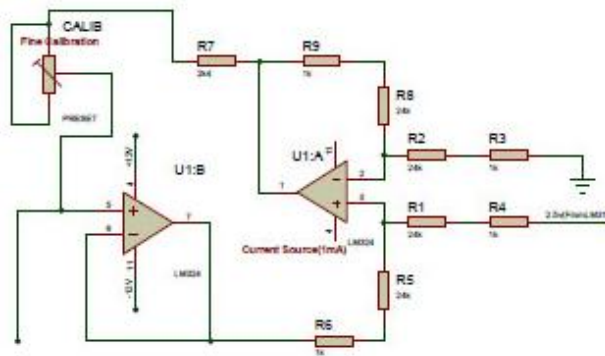


Fig. 2

This is accomplished as follows:

The operational amplifier A₁ (U1-A) and resistor R₁ through R₄ for a difference amplifier with a differential gain (G_{A1}) of 1v/v. A 2.5v precision voltage reference is applied to input of this difference amplifier. The output of op-amp A₂ (U1-B) serves as the difference amplifier's reference voltage. The voltage at the output of A₁ is shown in eq.1 below;

$$V_{outA1} = V_{REF} G_{A1} + V_{out2} \text{ ----- (1)}$$

Where;

V_{outA1} = A₁'s output voltage

V_{out2} = A₂'s output voltage

V_{REF} = Reference voltage at input

G_{A1} = 1v/v

Assuming

V_{out2} = V₂, and R₇ = R_{REF}

we get,

$$V_{RREF} = V_{OUTA1} - V_2$$

$$V_{RREF} = V_{REF}$$

Where;

V₂ = voltage at A₂'s input

V_{RREF} = voltage across R_{REF}

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The current used to bias the RTD assembly (I_{RREF}) is constant and independent of the voltage V_2 ,

$$I_{RREF} = V_{RREF} / R_{REF}$$

$$I_{RREF} = 1\text{mA}$$

5) *RTD Signal Conditioning Circuit:* The current excitation circuit excites the RTD element. The magnitude of the current source is turned to 1mA or less by adjusting R_{REF} . The RTD signal conditioning path is shown in fig.3 and fig.4 below.

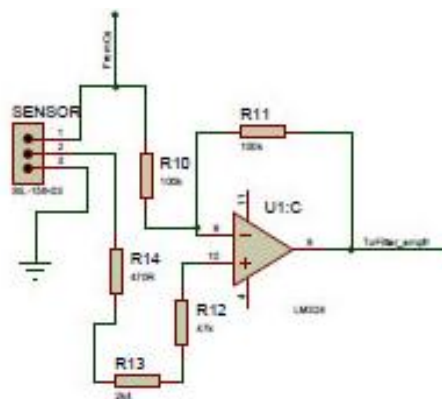


Fig. 3 RTD correct circuit.

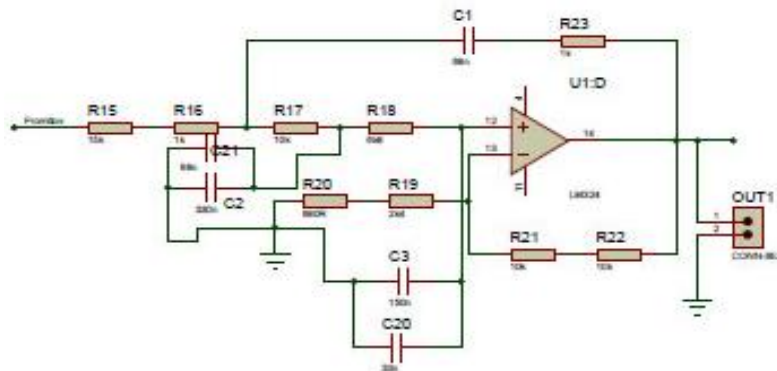


Fig. 4 Sallen-key filter

The voltage drop across RTD element is sensed by A3 (U1-C), and then gained and filtered by A4 (U1-D). With this circuit a 3 wire RTD element was selected. This configures minimizes error due to wire resistance and wire resistance drift over temperature. In this circuit RTD element equals 100Ω at 0°C . If the RTD is use to sensed the temperature over the range -200°C to 600°C . the resistance produced by the RTD would be between 18.5Ω and 313.7Ω giving a voltage across RTD between 18.5mv and 313.7mv [10].

The error contributed by wire resistance is subtracted from the signal with op-amp A3. The voltage signal at the output of A3 is filtered with 2nd order filter created with A4. It reduces the noise and prevents aliasing of high frequency signals. This filter uses a Sallen-key topology specially designed for high gain [11]. The capacitor divider formed by C1 and C3 improves the filters sensitivity to components variations. The voltage A4's output is nominally between 0.138v to 2.343v , which is less than V_{REF} (2.5v). This output is given to microcontroller.

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The complete signal conditioning circuit is shown in fig. 5 below;

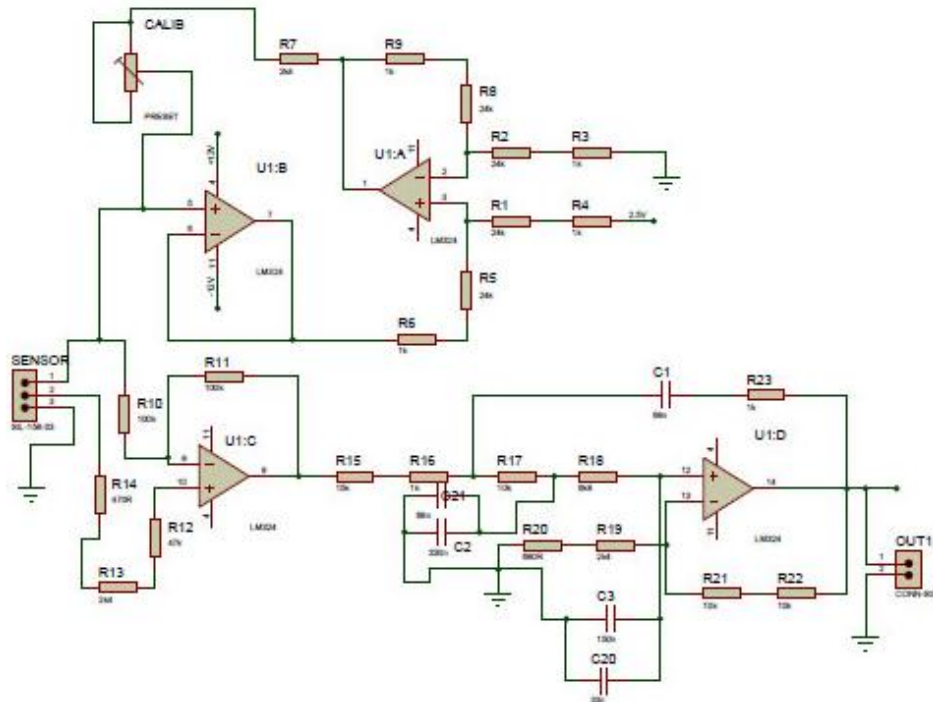


Fig. 5 complete signal conditioning circuit.

- 6) *Controller Section:* The analog value of temperature is given to microcontroller PIC16F876A, which has in built A/D convertor. The signal is processed inside the controller and given to display section and relay.
- 7) *Display Section:* Since it is essential to display the data recorded from the microcontroller, a liquid crystal display is used.
- 8) *Relay:* The output of the microcontroller is also given to relay through ULN2003A driver. The relay remains off until measured temperature reaches to set point. When it exceeds the set point temperature, it become on.

The complete circuit design of system is shown in fig. 6 below;

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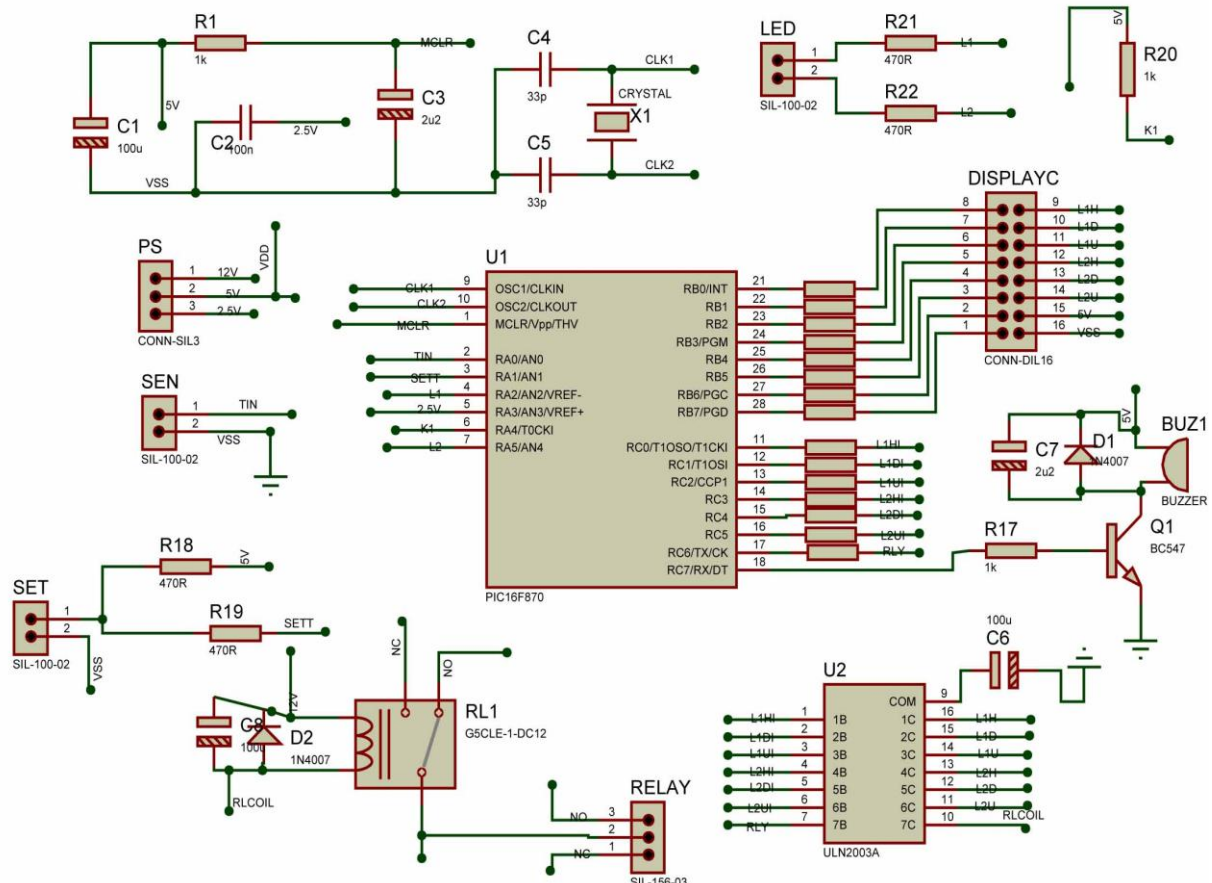


Fig. 6 complete circuit of designed system

B. Software Description

Software description for the present work is for outline monitoring and controlling and is developed in C language assembly language.

V. TESTING AND RESULT

When the fabrication process is completed and all the components have been mounted. Hardware testing was carried out. It was found that all the circuit working properly and perfect and there is no loose connection between the components.

Later on application testing was done with standard instruments. The result of this testing are tabulated before and after calibration in table1 and table2. UUC stand for unit under calibration. The graph plotted between measured and standard value are shown in fig7 and fig. 8 respectively.

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TABLE I

INPUT PT-100(WITHOUT CALLIBRATION)

SR NO	CALIBRATION POINT	VALUE ON UUC(°C)	VALUE ON STANDAR D(°C)	DEVIATION
1	50.00	51.2	50.8	0.4
2	100.00	101.00	99.8	1.2
3	150.00	150.2	149.1	1.1
4	200.00	201.2	200.5	0.7
5	250.00	251.00	250.2	0.8
6	300.00	300.2	299.3	0.9
7	350.00	350.7	349.8	0.9
8	400.00	398.2	399.2	-1.00

TABLE II

INPUT PT-100(WITH CALLIBRATION)

SR. NO	VALUE ON UUC(°C)	VALUE ON STANDAR D(°C)	DEVIATION
1	40	40	0
2	60	60	0
3	80	80	0
4	100	100	0
5	120	120	0
6	140	140	0
7	160	160	0
8	180	180	0
9	200	200	0
10	220	220	0
11	240	240	0
12	260	260	0
13	280	280	0
14	300	300	0
15	321	320	1
16	341	340	1
17	360	360	0
18	381	380	1
19	401	400	1

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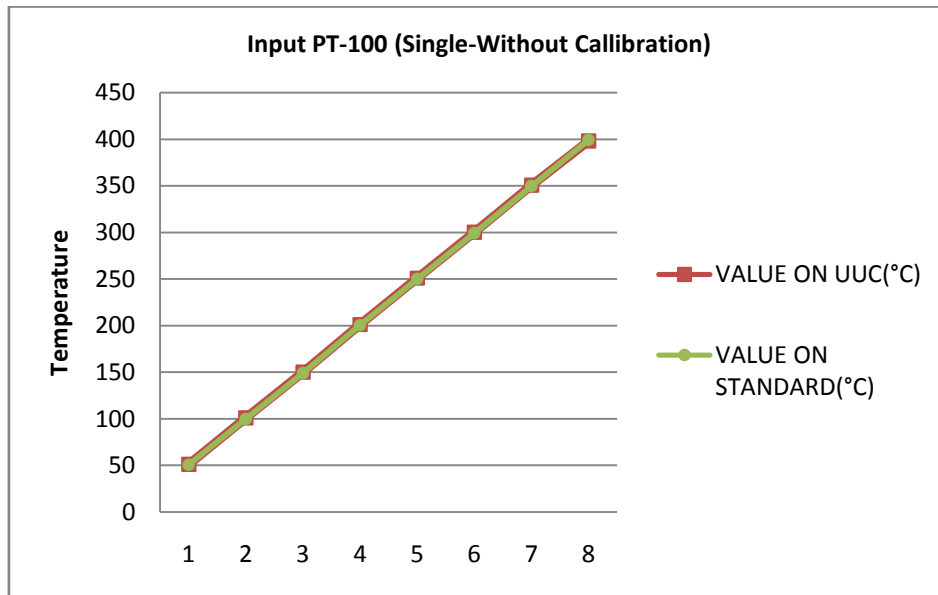


Fig. 7

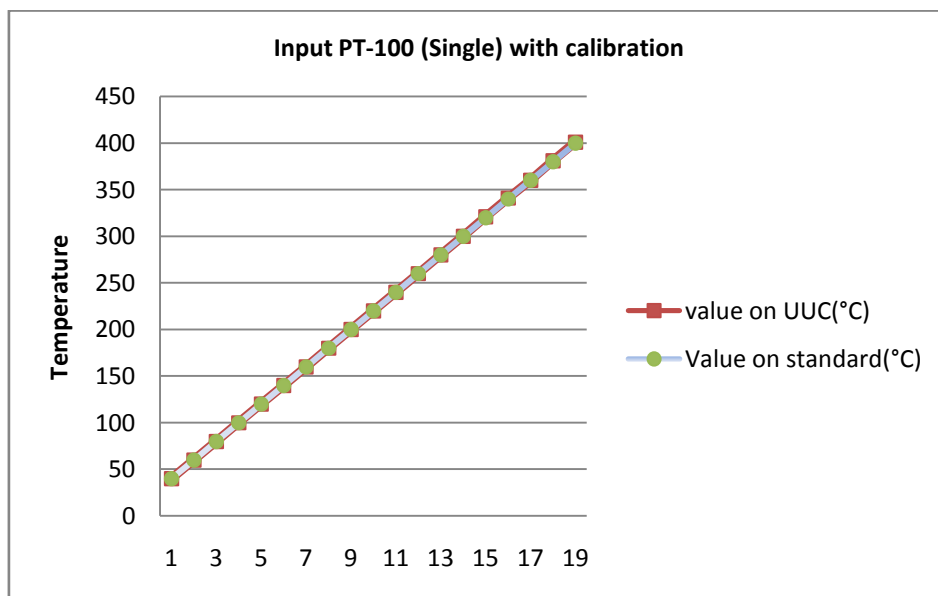


Fig. 8

These graph shows that reading of measured value is almost identical with standard value. The lower range side of temperature reading is and their slight deviation in upper range of temperature.

VI. CONCLUSION

In this paper a simple, low cost design of an embedded system for temperature controller using PIC 16F876A was designed. The sensor element used is Pt-100 RTD. The result of measuring value shows that its response is linear and accuracy is good. The system can be further enhanced by developing it for multi sensor designs, so that there can be



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choice of sensor as per the requirement and temperature range. Further it can be improve by making an arrangement for automatic control of temperature of source by remote sensor so that system can automatically adjust the temperature as set.

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